Fractional Order Differentiation And Robust Control Design Crone H Infinity And Motion Control Intelligent Systems Control And Automation Science And Engineering

This volume presents selected aspects of non-integer, or fractional order systems, whose analysis, synthesis and applications have increasingly become a real challenge for various research communities, ranging from science to engineering. The spectrum of applications of the fractional order calculus has incredibly expanded, in fact it would be hard to find a science/engineering-related subject area where the fractional calculus had not been incorporated. The content of the fractional calculus is ranged from pure mathematics to engineering implementations and so is the content of this volume. The volume is subdivided into six parts, reflecting particular aspects of the fractional order calculus. The first part contains a single invited paper on a new formulation of fractional-order descriptor observers for fractional-order descriptor continous LTI systems. The second part provides new elements to the mathematical theory of fractional-order systems. In the third part of this volume, a bunch of new results in approximation, modeling and simulations of fractional-order systems is given. The fourth part presents new solutions to some problems in controllability and control of non-integer order systems, in particular fractional PID-like control. The fifth part analyzes the stability of non-integer order systems and some new results are offered in this important respect, in particular for discrete-time systems. The final, sixth part of this volume presents a spectrum of applications of the noninteger order calculus, ranging from bi-fractional filtering, in particular of electromyographic signals, through the thermal diffusion and advection diffusion processes to the SIEMENS platform implementation. This volume's papers were all subjected to stimulating comments and discussions from the active audience of the RRNR'2014, the 6th Conference on Non-integer Order Calculus and Its Applications that was organized by the Department of Electrical, Control and Computer Engineering, Opole University of Technology, Opole, Poland.

Fractional order calculus is finding increasing interest in the control system community. Hardware realizations of fractional order controllers have sparked off a renewed zeal into the investigations of control system design in the light of fractional calculus. As such many notions of integer order LTI systems are being modified and extended to incorporate these new concepts. Computational Intelligence (CI) techniques have been applied to engineering problems to find solutions to many hitherto intractable conundrums and is a useful tool for dealing with problems of higher computational complexity. This book borders on the interface between CI techniques and fractional calculus, and looks at ways in which fractional order control systems may be designed or enhanced using CI based paradigms. To the best of the author's knowledge this is the first book of its kind exclusively dedicated to the application of computational intelligence techniques in fractional order systems and control. The book tries to assimilate various existing concepts in this nascent field of fractional order intelligent control and is aimed at researchers and post graduate students working in this field.

"Fractional-Order Nonlinear Systems: Modeling, Analysis and Simulation" presents a study of fractional-order chaotic systems accompanied by Matlab programs for simulating their state space trajectories, which are shown in the illustrations in the book. Description of the chaotic systems is clearly presented and their analysis and numerical solution are done in an easy-to-follow manner. Simulink models for the selected fractional-order systems are also presented. The readers will understand the fundamentals of the fractional calculus, how real dynamical systems can be described using fractional derivatives and fractional differential equations, how such equations can be solved, and how to simulate and explore chaotic systems of fractional order. The book addresses to mathematicians, physicists, engineers, and other scientists interested in chaos phenomena or in fractional-order systems. It can be used in courses on dynamical systems, control theory, and applied mathematics at graduate or postgraduate level. Ivo Petráš is an Associate Professor of automatic control and the Director of the Institute of Control and Informatization of Production Processes, Faculty of BERG, Technical University of Košice, Slovak Republic. His main research interests include control systems, industrial automation, and applied mathematics.

The book presents selected, extended and peer reviewed papers from the International Multiconference on System, Automation and Control held Leipzig in 2018. These are complemented with solicited contributions by international experts. Main topics are automatic control, robotics, synthesis of automation systems. Application examples range from man-machine interaction, mechatronics, on to biological and economical models.

In the last two decades, fractional (or non integer) differentiation has played a very important role in various fields such as mechanics, electricity, chemistry, biology, economics, control theory and signal and image processing. For example, in the last three fields, some important considerations such as modelling, curve fitting, filtering, pattern recognition, edge detection, identification, stability, controllability, observability and robustness are now linked to long-range dependence phenomena. Similar progress has been made in other fields listed here. The scope of the book is thus to present the state of the art in the study of fractional systems and the application of fractional differentiation. As this volume covers recent applications of fractional calculus, it will be of interest to engineers, scientists, and applied mathematicians.

Positive Systems

An Introduction

Robotics Research

Advances in Robust Fractional Control

Modeling, Analysis and Simulation

Informatics in Control, Automation and Robotics

Fault-tolerant Control and Diagnosis for Integer and Fractional-order Systems

The book focuses the latest endeavours relating researches and developments conducted in fields of Control, Robotics and Automation. Through more than twenty revised and extended articles, the present book aims to provide the most up-to-date state-of-art of the aforementioned fields allowing researcher, PhD students and engineers not only updating their knowledge but also benefiting from the source of inspiration that represents the set of selected articles of the book. The deliberate intention of editors to cover as well theoretical facets of those fields as their practical accomplishments and implementations offers the benefit of gathering in a same volume a factual and well-balanced prospect of nowadays research in those topics. A special attention toward " Intelligent Robots and Control " may characterize another benefit of this book.

This book presents solutions to control problems in a number of robotic systems and provides a wealth of worked-out examples with full analytical and numerical details, graphically illustrated to aid in reader comprehension. It also presents relevant studies on and applications of robotic system control approaches, as well as the latest findings from interdisciplinary theoretical studies. Featuring chapters on advanced control (fuzzy, neural, backstepping, sliding mode, adaptive, predictive, diagnosis, and fault-tolerant control), the book will equip readers to easily tailor the techniques to their own applications. Accordingly, it offers a valuable resource for researchers, engineers, and students in the field of robotic systems.

This book offers a timely overview of fractional calculus applications, with a special emphasis on fractional derivatives with Mittag-Leffler kernel. The different contributions, written by applied mathematicians, physicists and engineers, offers a snapshot of recent research in the field, highlighting the current methodological frameworks together with applications in different fields of science and engineering, such as chemistry, mechanics, epidemiology and more. It is intended as a timely guide and source of inspiration for graduate students and researchers in the above-mentioned areas.

This book is focused on fractional order systems. Historically, fractional calculus has been recognized since the inception of regular calculus, with the first written reference dated in September 1695 in a letter from Leibniz to L ' Hospital. Nowadays, fractional calculus has a wide area of applications in areas such as physics, chemistry, bioengineering, chaos theory, control systems engineering, and many others. In all those applications, we deal with fractional order systems in general. Moreover, fractional calculus plays an important role even in complex systems and therefore allows us to develop better descriptions of real-world phenomena. On that basis, fractional order systems are ubiquitous, as the whole real world around us is fractional. Due to this reason, it is urgent to consider almost all systems as fractional order systems. This Special Issue explores applications of such systems to control, synchronization, and various mathematical models, as for instance, MRI, long memory process, diffusion.

In the last two decades fractional differential equations have been used more frequently in physics, signal processing, fluid mechanics, viscoelasticity, mathematical biology, electro chemistry and many others. It opens a new and more realistic way to capture memory dependent phenomena and irregularities inside the systems by using more sophisticated mathematical analysis. This monograph is based on the authors ' work on stabilization and control design for continuous and discrete fractional order systems. The initial two chapters and some parts of the third chapter are written in tutorial fashion, presenting all the basic concepts of fractional order system and a brief overview of sliding mode control of fractional order systems. The other parts contain deal with robust finite time stability of fractional order systems, integral sliding mode control of fractional order systems, co-operative control of multi-agent systems modeled as fractional differential equation, robust stabilization of discrete fractional order systems, high performance control using soft variable structure control and contraction analysis by integer and fractional order infinitesimal variations.

Analysis, Modeling and Stability of Fractional Order Differential Systems 2

Basic Theory

Roadmap to Improve Tracking-Trajectory Performance in the Presence of External Disturbances

Fractional Order Motion Controls

Discrete Fractional Calculus

Distributed-Order Dynamic Systems

Implicit Fractional Differential and Integral Equations

Mathematical Techniques of Fractional Order Systems illustrates advances in linear and nonlinear fractional-order systems relating to many interdisciplinary applications, including biomedical, control, circuits, electromagnetics and security. The book covers the mathematical background and literature survey of fractional-order calculus and generalized fractional-order circuit theorems from different perspectives in design, analysis and realizations, nonlinear fractional-order circuits and systems, the fractional-order memristive circuits and systems in design, analysis, emulators, simulation and experimental results. It is primarily meant for researchers from academia and industry, and for those working in areas such as control engineering, electrical engineering, computer science and information technology. This book is ideal for researchers working in the area of both continuous-time and discrete-time dynamics and chaotic systems. Discusses multidisciplinary applications with new fundamentals, modeling, analysis, design, realization and experimental results Includes circuits and systems based on new nonlinear elements Covers most of the linear and nonlinear fractional-order theorems that will solve many scientific issues for researchers Closes the gap between theoretical approaches and real-world applications Provides MATLAB® and Simulink code for many applications in the book

This multi-volume handbook is the most up-to-date and comprehensive reference work in the field of fractional calculus and its numerous applications. This fourth volume collects authoritative chapters covering several applications of fractional calculus in physics, including classical and continuum mechanics.

The main subject of the monograph is the fractional calculus in the discrete version. The volume is divided into three main parts. Part one contains a theoretical introduction to the classical and fractional-order discrete calculus where the fundamental role is played by the backward difference and sum. In the second part, selected applications of the discrete fractional calculus in the discrete system control theory are presented. In the discrete system identification, analysis and synthesis, one can consider integer or fractional models based on the fractional-order difference equations. The third part of the book is devoted to digital image processing.

This volume contains the proceedings of the KKA 2017 the 19th Polish Control Conference, organized by the Department of Automatics and Biomedical Engineering, AGH University of Science and Technology in Kraków, Poland on June 18–21, 2017, under the auspices of the Committee on Automatic Control and Robotics of the Polish Academy of Sciences, and the Commission for Engineering Sciences of the Polish Academy of Arts and Sciences. Part 1 deals with general issues of modeling and control, notably flow modeling and control, sliding mode, predictive, dual, etc. control. In turn, Part 2 focuses on optimization, estimation and prediction for control. Part 3 is concerned with autonomous vehicles, while Part 4 addresses applications. Part 5 discusses computer methods in control, and Part 6 examines fractional order calculus in the modeling and control of dynamic systems. Part 7 focuses on modern robotics. Part 8 deals with modeling and identification, while Part 9 deals with problems related to security, fault detection and diagnostics. Part 10 explores intelligent systems in automatic control, and Part 11 discusses the use of control tools and techniques in biomedical engineering. Lastly, Part 12 considers engineering education and teaching with regard to automatic control and robotics.

This book touches upon various aspects of a very interesting, and growing in popularity category of models of dynamical systems. These are the so-called fractional-order systems. Such models are not only relevant for many fields of science and technology, but may also find numerous applications in other disciplines applying the mathematical modelling tools. Thus, the book is intended for a very wide audience of professionals who want to expand their knowledge of systems modelling and its applications. The book includes the selections of papers presented at the International Conference on Fractional Calculus and its Applications organized by the Warsaw University of Technology and was held online on 6–8 September 2021. The International Conference on Fractional Calculus and its Applications (ICFDA) has an almost twenty years history. It started in Bordeaux (France) in 2004, followed by Porto (Portugal) 2006, Istanbul (Turkey) 2008, Badajoz (Spain) 2010, Nanjing (China) 2012, Catania (Italy) 2014, Novi Sad (Serbia) 2016, Amman (Jordan) 2018. Next ICFDA was planned in 2020 in Warsaw (Poland), but COVID-19 pandemic shifted it to 6–8 September 2021. Hence, the organizers were forced to change the form of the conference to the online one. In the volume twenty eight high-quality research papers presented during the ICFDA 2021 eleven Regular Sessions with an additional online Discussion Session are presented. The presented papers are scientifically inspiring, leading to new fruitful ideas. They cover a very broad range of many disciplines. Nowadays, and especially in such a subject as fractional calculus, it is very difficult to assign papers to specific scientific areas. So, many of the papers included have an interdisciplinary character.

Existence and Stability

Trends and Applications in Science and Engineering

New Trends in Robot Control

Analysis, Modeling and Stability of Fractional Order Differential Systems 1

Fractional Order Systems

Theory and Applications (POSTA 2016) Rome, Italy, September 14-16, 2016

Fractional Signals and Systems

Covering fractional order theory, simulation and experiments, this book explains how fractional order modelling and fractional order controller design compares favourably with traditional velocity and position control systems. The authors systematically compare the two approaches using applied fractional calculus. Stability theory in fractional order controllers design is also analysed. Presents material suitable for a variety of real-world applications, including hard disk drives, vehicular controls, robot control and micropositioners in DNA microarray analysis Includes extensive experimental results from both lab bench level tests and industrial level, mass-production-ready implementations Covers detailed derivations and numerical simulations for each case Discusses feasible design specifications, ideal for practicing engineers The book also covers key topics including: fractional order disturbance cancellation and adaptive learning control studies for external disturbances; optimization approaches for nonlinear system control and design schemes with backlash and friction. Illustrations and experimental validations are included for each of the proposed control schemes to enable readers to develop a clear understanding of the approaches covered, and move on to apply them in real-world scenarios.

The book illustrates the theoretical results of fractional derivatives via applications in signals and systems, covering continuous and discrete derivatives, and the corresponding linear systems. Both time and frequency analysis are presented. Some advanced topics are included like derivatives of stochastic processes. It is an essential reference for researchers in mathematics, physics, and engineering.

This monograph presents design methodologies for (robust) fractional control systems. It shows the reader how to take advantage of the superior flexibility of fractional control systems compared with integer-order systems in achieving more challenging control requirements. There is a high degree of current interest in fractional systems and fractional control arising from both academia and industry and readers from both milieux are catered to in the text. Different design approaches having in common a trade-off between robustness and performance of the control system are considered explicitly. The text generalizes methodologies, techniques and theoretical results that have been successfully applied in classical (integer) control to the fractional case. The first part of Advances in Robust Fractional Control is the more industrially oriented. It focuses on the design of fractional controllers for integer processes. In particular, it considers fractional-order proportional-integral-derivative controllers, because integer-order PID regulators are, undoubtedly, the controllers most frequently adopted in industry. The second part of the book deals with a more general approach to fractional control systems, extending techniques (such as H-infinity optimal control and optimal input–output inversion based control) originally devised for classical integer-order control. Advances in Robust Fractional Control will be a useful reference for the large number of academic researchers in fractional control, for their industrial counterparts and for graduate students who want to learn more about this subject.

This multi-volume handbook is the most up-to-date and comprehensive reference work in the field of fractional calculus and its numerous applications. This first volume collects authoritative chapters covering the mathematical theory of fractional calculus, including fractional-order operators, integral transforms and equations, special functions, calculus of variations, and probabilistic and other aspects.

This book aims to propose implementations and applications of Fractional Order Systems (FOS). It is well known that FOS can be applied in control applications and systems modeling, and their effectiveness has been proven in many theoretical works and simulation routines. A further and mandatory step for FOS real world utilization is their hardware implementation and applications on real systems modeling. With this viewpoint, introductive chapters on FOS are included, on the definition of stability region of Fractional Order PID Controller and Chaotic FOS, followed by the practical implementation based on Microcontroller, Field Programmable Gate Array, Field Programmable Analog Array and Switched Capacitor. Another section is dedicated to FO modeling of Ionic Polymeric Metal Composite (IPMC). This new material may have applications in robotics, aerospace and biomedicine.

Modeling and Control Applications

Robust Adaptive Control for Fractional-Order Systems with Disturbance and Saturation

Stability, Simulation, Applications and Perspectives

Automation, Control and Energy Efficiency in Complex Systems

Fractional-order Systems and PID Controllers

Fractional Order Differentiation and Robust Control Design

Numerical Methods for Fractional Differentiation

This multi-volume handbook is the most up-to-date and comprehensive reference work in the field of fractional calculus and its numerous applications. This sixth volume collects authoritative chapters covering several applications of fractional calculus in control theory, including fractional controllers, design methods and toolboxes, and a large number of engineering applications of control. Multi-Chaos, Fractal and Multi-Fractional Artificial Intelligence of Different Complex Systems addresses different uncertain processes inherent in the complex systems, attempting to provide global and robust optimized solutions distinctively through multifarious methods, technical analyses, modeling, optimization processes, numerical simulations, case studies as well as applications including theoretical aspects of complexity. Foregrounding Multi-chaos, Fractal and Multi-fractional in the era of Artificial Intelligence (AI), the edited book deals with multi- chaos, fractal, multifractional, fractional calculus, fractional operators, quantum, wavelet, entropy-based applications, artificial intelligence, mathematics-informed and data driven processes aside from the means of modelling, and simulations for the solution of multifaceted problems characterized by nonlinearity, non-regularity and self-similarity, frequently encountered in different complex systems. The fundamental interacting components underlying complexity, complexity thinking, processes and theory along with computational processes and technologies, with machine learning as the core component of AI demonstrate the enabling of complex data to augment some critical human skills. Appealing to an interdisciplinary network of scientists and researchers to disseminate the theory and application in medicine, neurology, mathematics, physics, biology, chemistry, information theory, engineering, computer science, social sciences and other far-reaching domains, the overarching aim is to empower out-of-the-box thinking through multifarious methods, directed towards paradoxical situations, uncertain processes, chaotic, transient and nonlinear dynamics of complex systems. Constructs and presents a multifarious approach for critical decision-making processes embodying paradoxes and uncertainty. Includes a combination of theory and applications with regard to multi-chaos, fractal and multi-fractional as well as AI of different complex systems and many-body systems. Provides readers with a bridge between application of advanced computational mathematical methods and AI based on comprehensive analyses and broad theories.

This book studies selected advanced flight control schemes for an uncertain quadrotor unmanned aerial vehicle (UAV) systems in the presence of constant external disturbances, parametric uncertainties, measurement noise, time-varying external disturbances, and random external disturbances. Furthermore, in all the control techniques proposed in this book, it includes the simulation results with comparison to other nonlinear control schemes recently developed for the tracking control of a quadrotor UAV. The main contributions of the present book for quadrotor UAV systems are as follows: (i) the proposed control methods are based on the high-order sliding mode controller (SMC) and hybrid control algorithm with an optimization method. (ii) the finite-time control schemes are developed by using fast terminal SMC (FTSMC), nonsingular FTSMC (NFTSMC), global time-varying SMC, and adaptive laws. (iii) the fractional-order flight control schemes are developed by using the fractional-order calculus theory, super twisting algorithm, NFTSMC, and the SMC. This book covers the research history and importance of quadrotor system subject to system uncertainties, external wind disturbances, and noise measurements, as well as the research status of advanced flight control methods, adaptive flight control methods, and flight control based on fractional-order theory. The book would be interesting to most academic undergraduate, postgraduates, researchers on flight control for drones and applications of advanced controllers in engineering field. This book presents a must-survey for advanced finite-time control for quadrotor system. Some parts of this book have the potential of becoming the courses for the modelling and control of autonomous flying machines. Readers (academic researcher, undergraduate student, postgraduate student, MBA/executive, and education practitioner) interested in nonlinear control methods find this book an investigation. This book can be used as a good reference for the academic research on the control theory, drones, terminal sliding mode control, and related to this or used in Ph.D. study of control theory and their application in field engineering.

The book presents the newest results of the major world research groups working in the area of Variable Structure Systems and Sliding Mode Control (VSS/SMC). The research activity of these groups is coordinated by the IEEE Technical Committee on Variable Structure Systems (VSS) and Sliding Modes (SM). The presented results include the reports of the research groups collaborating in a framework of the Unión European Union – México project of Fondo de Cooperación Internacional en Ciencia y Tecnología (FONCICyT) 93302 titled "Automatization and Monitoring of Energy Production Processes via Sliding Mode Control". The book starts with the overview of the sliding mode control concepts and algorithms that were developed and discussed in the last two decades The research papers are combined in three sections: Part I: VSS and SM Algorithms and their Analysis Part II: SMC Design Part III: Applications of VSS and SMC The book will be of interests of engineers, researchers and graduate students working in the area of the control systems design. Novel mathematical theories and engineering concepts of control systems are rigorously discussed and supported by numerous applications to practical tasks.

This book introduces an original fractional calculus methodology ('the infinite state approach') which is applied to the modeling of fractional order differential equations (FDEs) and systems (FDSs). Its modeling is based on the frequency distributed fractional integrator, while the resulting model corresponds to an integer order and infinite dimension state space representation. This original modeling allows the theoretical concepts of integer order systems to be generalized to fractional systems, with a particular emphasis on a convolution formulation.

Fractional-order Systems and Controls

Fractional Order Control and Synchronization of Chaotic Systems

Theoretical Developments and Applications in Physics and Engineering

Applications in Control and Image Processing

Fractional Modeling and Controller Design of Robotic Manipulators

Volume 1

Mathematical Techniques of Fractional Order Systems

ISRR, the "International Symposium on Robotics Research", is one of robotics pioneering Symposia, which has established over the past two decades some of the field's most fundamental and lasting contributions. This book presents the results of the seventeenth edition of "Robotics Research" ISRR15, offering a collection of a broad range of topics in robotics. The content of the contributions provides a wide coverage of the current state of robotics research.: the advances and challenges in its theoretical foundation and technology basis, and the developments in its traditional and new emerging areas of applications. The diversity, novelty, and span of the work unfolding in these areas reveal the field's increased maturity and expanded scope and define the state of the art of robotics and its future direction.

The book reports on the latest advances in and applications of fractional order control and synchronization of chaotic systems, explaining the concepts involved in a clear, matter-of-fact style. It consists of 30 original contributions written by eminent scientists and active researchers in the field that address theories, methods and applications in a number of research areas related to fractional order control and synchronization of chaotic systems, such as: fractional chaotic systems, hyperchaotic systems, complex systems, fractional order discrete chaotic systems, chaos control, chaos synchronization, jerk circuits, fractional chaotic systems with hidden attractors, neural network, fuzzy logic controllers, behavioral modeling, robust and adaptive control, sliding mode control, different types of synchronization, circuit realization of chaotic systems, etc. In addition to providing readers extensive information on chaos fundamentals, fractional calculus, fractional differential equations, fractional control and stability, the book also discusses key applications of fractional order chaotic systems, as well as multidisciplinary solutions developed via control modeling. As such, it offers the perfect reference guide for graduate students, researchers and practitioners in the areas of fractional order control systems and fractional order chaotic systems.

This book presents high-quality original contributions on positive systems, including topics such as: monotone dynamical systems in mathematical biology and game theory; mathematical developments for networked systems in biology, chemistry and the social sciences; linear and nonlinear positive operators; dynamical analysis, observation and control of positive distributed parameter systems; stochastic realization theory; biological systems with positive variables and positive controls; iterated function systems; nonnegative dynamic processes; and dimensioning problems for collaborative systems. The book comprises a selection of the best papers presented at the POSTA 2016, the 5th International Symposium on Positive Systems, which was held in Rome, Italy, in September 2016. This conference series represents a targeted response to the growing need for research that reports on and critically discusses a wide range of topics concerning the theory and applications of positive systems.

This book introduces an original fractional calculus methodology ('the infinite state approach') which is applied to the modeling of fractional order differential equations (FDEs) and systems (FDSs). Its modeling is based on the frequency distributed fractional integrator, while the resulting model corresponds to an integer order and infinite dimension state space representation. This original modeling allows the theoretical concepts of integer order systems to be generalized to fractional systems, with a particular emphasis on a convolution formulation. With this approach, fundamental issues such as system state interpretation and system initialization - long considered to be major theoretical pitfalls - have been solved easily. Although originally introduced for numerical simulation and identification of FDEs, this approach also provides original solutions to many problems such as the initial conditions of fractional derivatives, the uniqueness of FDS transients, formulation of analytical transients, fractional differentiation of functions, state observation and control, definition of fractional energy, and Lyapunov stability analysis of linear and nonlinear fractional order systems. This second volume focuses on the initialization, observation and control of the distributed state, followed by stability analysis of fractional differential systems.

Fractional-order Systems and Controls details the use of fractional calculus in the description and modeling of systems, and in a range of control design and practical applications. It is largely self-contained, covering the fundamentals of fractional calculus together with some analytical and numerical techniques and providing MATLAB® codes for the simulation of fractional-order control (FOC) systems. Many different FOC schemes are presented for control and dynamic systems problems. Practical material relating to a wide variety of applications is also provided. All the control schemes and applications are presented in the monograph with either system simulation results or real experimental results, or both. Fractional-order Systems and Controls provides readers with a basic understanding of FOC concepts and methods, so they can extend their use of FOC in other industrial system applications, thereby expanding their range of disciplines by exploiting this versatile new set of control techniques.

Advanced Robust Nonlinear Control Approaches for Quadrotor Unmanned Aerial Vehicle

Using Scilab and Curve Fitting Based Approximation Techniques

CRONE, H-infinity and Motion Control

Fractional-Order Nonlinear Systems

Multi-Chaos, Fractal and Multi-Fractional Artificial Intelligence of Different Complex Systems

Sliding Modes after the first Decade of the 21st Century

Stabilization and Control of Fractional Order Systems: A Sliding Mode Approach

Fractional Order Differentiation and Robust Control DesignCRONE, H-infinity and Motion ControlSpringer

A treatise on investigating tracking control and synchronization control of fractional-order nonlinear systems with system uncertainties, external disturbance, and input saturation Robust Adaptive Control for Fractional-Order Systems, with Disturbance and Saturation provides the reader with a good understanding on how to achieve tracking control and synchronization control of fractional-order nonlinear systems with system uncertainties, external disturbance, and input saturation. Although some texts have touched upon control of fractional-order systems, the issues of input saturation and disturbances have rarely been considered together. This book offers chapter coverage of fractional calculus and fractional-order systems; fractional-order PID controller and fractional-order disturbance observer; design of fractional-order controllers for nonlinear chaotic systems and some applications; sliding mode control for fractional-order nonlinear systems based on disturbance observer; disturbance observer based neural control for an uncertain fractional-order rotational mechanical system; adaptive neural tracking control for uncertain fractional-order chaotic systems subject to input saturation and disturbance; stabilization control of continuous-time fractional positive systems based on disturbance observer; sliding mode synchronization control for fractional-order chaotic systems with disturbance; and more. Based on the approximation ability of the neural network (NN), the adaptive neural control schemes are reported for uncertain fractional-order nonlinear systems Covers the disturbance estimation techniques that have been developed to alleviate the restriction faced by traditional feedforward control and reject the effect of external disturbances for uncertain fractional-order nonlinear systems By combining the NN with the disturbance observer, the disturbance observer based adaptive neural control schemes have been studied for uncertain fractional-order nonlinear systems with unknown disturbances Considers, together, the issue of input saturation and the disturbance for the control of fractional-order nonlinear systems in the present of system uncertainty, external disturbance, and input saturation Robust Adaptive Control for Fractional-Order Systems, with Disturbance and Saturation can be used as a reference for the academic research on fractional-order nonlinear systems or used in Ph.D. study of control theory and engineering.

This book is about algebraic and differential methods, as well as fractional calculus, applied to diagnose and reject faults in nonlinear systems, which are of integer or fractional order. This represents an extension of a very important and widely studied problem in control theory, namely fault diagnosis and rejection (using differential algebraic approaches), to systems presenting fractional dynamics, i.e. systems whose dynamics are represented by derivatives and integrals of non-integer order. The authors offer a thorough overview devoted to fault diagnosis and fault-tolerant control applied to fractional-order and integer-order dynamical systems, and they introduce new methodologies for control and observation described by fractional and integer models, together with successful simulations and real-time applications. The basic concepts and tools of mathematics required to understand the methodologies proposed are all clearly introduced and explained. Consequently, the book is useful as supplementary reading in courses of applied mathematics and nonlinear control theory. This book is meant for engineers, mathematicians, physicists and, in general, to researchers and postgraduate students in diverse areas who have a minimum knowledge of calculus. It also contains advanced topics for researchers and professionals interested in the area of states and faults estimation.

This book deals with the existence and stability of solutions to initial and boundary value problems for functional differential and integral equations and inclusions involving the Riemann-Liouville, Caputo, and Hadamard fractional derivatives and integrals. A wide variety of topics is covered in a mathematically rigorous manner making this work a valuable source of information for graduate students and researchers working with problems in fractional calculus. ContentsPreliminary Background Nonlinear Implicit Fractional Differential Equations Impulsive Nonlinear Implicit Fractional Differential Equations Boundary Value Problems for Nonlinear Implicit Fractional Differential Equations Boundary Value Problems for Impulsive NIFDE Integrable Solutions for Implicit Fractional Differential Equations Partial Hadamard Fractional Integral Equations and Inclusions Stability Results for Partial Hadamard Fractional Integral Equations and Inclusions Hadamard–Stieltjes Fractional Integral Equations Ulam Stabilities for Random Hadamard Fractional Integral Equations

This book provides an overview of the research done and results obtained during the last ten years in the fields of fractional systems control, fractional PI and PID control, robust and CRONE control, and fractional path planning and path tracking. Coverage features theoretical results, applications and exercises. The book will be useful for post-graduate students who are looking to learn more on fractional systems and control. In addition, it will also appeal to researchers from other fields interested in increasing their knowledge in this area.

Systems, Automation, and Control

Fractional Derivatives with Mittag-Leffler Kernel

The Infinite State Approach

Applications in Physics

Fundamentals and Applications

Fundamentals of Fractional Calculus and Differential Algebra with Real-Time Applications

Advances in Fractional Calculus

Distributed-order differential equations, a generalization of fractional calculus, are of increasing importance in many fields of science and engineering from the behaviour of complex dielectric media to the modelling of nonlinear systems. This Brief will broaden the toolbox available to researchers interested in modeling, analysis, control and filtering. It contains contextual material outlining the progression from integer-order, through fractional-order to distributed-order systems. Stability issues are addressed with graphical and numerical results highlighting the fundamental differences between constant-, integer-, and distributed-order treatments. The power of the distributed-order model is demonstrated with work on the stability of noncommensurate-order linear time-invariant systems. Generic applications of the distributed-order operator follow: signal processing and viscoelastic damping of a mass – spring set up. A new general approach to discretization of distributed-order derivatives and integrals is described. The Brief is rounded out with a consideration of likely future research and applications and with a number of MATLAB® codes to reduce repetitive coding tasks and encourage new workers in distributed-order systems.

This book presents a detailed study on fractional-order, set-point, weighted PID control strategies and the development of curve-fitting-based approximation techniques for fractional-order parameters. Furthermore, in all the cases, it includes the Scilab-based commands and functions for easy implementation and better understanding, and to appeal to a wide range of readers working with the software. The presented Scilab-based toolbox is the first toolbox for fractional-order systems developed in open-source software. The toolboxes allow time and frequency domains as well as stability analysis of the fractional-order systems and controllers. The book also provides real-time examples of the control of process plants using the developed fractional-order based PID control strategies and the approximation techniques. The book is of interest to readers in the areas of fractional-order controllers, approximation techniques, process modeling, control, and optimization, both in industry and academia. In industry, the book is particularly valuable in the areas of research and development (R&D) as well as areas where PID controllers suffice – and it should be noted that around 80% of low-level controllers in industry are PID based. The book is also useful where conventional PIDs are constrained, such as in industries where long-term delay and non-linearity are present. Here it can be used for the design of controllers for real-time processes. The book is also a valuable teaching and learning resource for undergraduate and postgraduate students.

This book is aimed at serving researchers, engineers, scientists, and engineering graduate and PhD students of engineering and physical science together with individuals interested in engineering and science. This book focuses on the application of engineering methods to complex systems including transportation, building, and manufacturing, with approaches representing a wide variety of disciplines of engineering and science. Throughout the book, great emphases are placed on engineering applications of complex systems, as well as the methodologies of automation, including artificial intelligence, automated and intelligent control, energy analysis, energy modelling, energy management, and optimised energy efficiency. The significant impact of recent studies that have been selected for presentation are of high interest in engineering complex systems. An attempt has been made to expose the reading audience of engineers and researchers to a broad range of theoretical and practical topics. The topics contained in the present book are of speci fi c interest to engineers who are seeking expertise in transportation, building, and manufacturing technologies as well as mathematical modelling of complex systems, engineering approaches to engineering complex problems, automation via artificial intelligence methods, automated and intelligent control, and energy systems. The primary audience of this book are researchers, graduate students, and engineers in mechanical engineering, control engineering, computer engineering, electrical engineering, and science disciplines. In particular, the book can be used for training graduate and PhD students as well as senior undergraduate students to enhance their knowledge by taking a graduate or advanced undergraduate course in the areas of complex systems, control systems, energy systems, and engineering applications. The covered research topics are also of interest to engineers and academia who are seeking to expand their expertise in these areas.

This book discusses numerical methods for solving partial differential and integral equations, as well as ordinary differential and integral equations, involving fractional differential and integral operators. Differential and integral operators presented in the book include those with exponential decay law, known as Caputo – Fabrizio differential and integral operators, those with power law, known as Riemann – Liouville fractional operators, and those for the generalized Mittag – Leffler function, known as the Atangana – Baleanu fractional operators. The book reviews existing numerical schemes associated with fractional operators including those with power law, while also highlighting new trends in numerical schemes for recently introduced differential and integral operators. In addition, the initial chapters address useful properties of each differential and integral fractional operator. Methods discussed in the book are subsequently used to solved problems arising in many fields of science, technology, and engineering, including epidemiology, chaos, solitons, fractals, diffusion, groundwater, and fluid mechanics. Given its scope, the book offers a valuable resource for graduate students of mathematics and engineering, and researchers in virtually all fields of science, technology, and engineering, as well as an excellent addition to libraries.

Fractional Order Systems: Optimization, Control, Circuit Realizations and Applications consists of 21 contributed chapters by subject experts. Chapters offer practical solutions and novel methods for recent research problems in the multidisciplinary applications of fractional order systems, such as FPGA, circuits, memristors, control algorithms, photovoltaic systems, robot manipulators, oscillators, etc. This book is ideal for researchers working in the modeling and applications of both continuous-time and discrete-time dynamics and chaotic systems. Researchers from academia and industry who are working in research areas such as control engineering, electrical engineering, mechanical engineering, computer science, and information technology will find the book most informative. Discusses multi-disciplinary applications with new fundamentals, modeling, analysis, design, realization and experimental results Includes new circuits and systems based on the new nonlinear elements Covers most of the linear and nonlinear fractional-order theorems that will solve many scientific issues for researchers Closes the gap between theoretical approaches and real-world applications Provides MATLAB® and Simulink code for many of the applications in the book

Advances in Modelling and Control of Non-integer-Order Systems

Optimization, Control, Circuit Realizations and Applications

14th International Conference, ICINCO 2017 Madrid, Spain, July 26-28, 2017 Revised Selected Papers

State of the Art

Proceedings of KKA 2017—The 19th Polish Control Conference, Krak ó w, Poland, June 18 – 21, 2017

Applications in Control

6th Conference on Non-integer Order Calculus and Its Applications, 2014 Opole, Poland

This book at hand is an appropriate addition to the field of fractional calculus applied to control systems. If an engineer or a researcher wishes to delve into fractional-order systems, then this book has many collections of such systems to work upon, and this book also tells the reader about how one can convert an

integer-order system into an appropriate fractional-order one through an efficient and simple algorithm. If the reader further wants to explore the controller design for the fractional-order systems, then for them, this book provides a variety of controller design strategies. The use of fractional-order derivatives and integrals in control theory leads to better results than integer-order approaches and hence provides solid motivation for further development of control theory. Fractional-order models are more useful than the integer-order models when accuracy is of paramount importance. Real-time experimental validation of controller design strategies for the fractional-order plants is available. This book is beneficial to the academic institutes for postgraduate and advanced research-level that need a specific textbook on fractional control and its applications in srobotic manipulators. The book is also a valuable teaching and learning resource for undergraduate and postgraduate students.

Intelligent Fractional Order Systems and Control

With Hardware Validation

Proceedings of the International Conference on Fractional Differentiation and its Applications (ICFDA'21)

Trends in Advanced Intelligent Control, Optimization and Automation