

## Modeling And Control Of An Unmanned Underwater Vehicle

Petri nets are widely used in modeling, analysis, and control of discrete event systems arising from manufacturing, transportation, computer and communication networks, and web service systems. However, Petri net models for practical systems can be very large, making it difficult to apply such models to real-life problems. System Modeling and Control with Resource-Oriented Petri Nets introduces a new resource-oriented Petri net (ROPN) model that was developed by the authors. Not only does it successfully reduce model size, but it also offers improvements that facilitate effective modeling, analysis, and control of automated and reconfigurable manufacturing systems. Presenting the latest research in this novel approach, this cutting-edge volume provides proven theories and methodologies for implementing cost and time-saving improvements to contemporary manufacturing systems. It provides effective tools for deadlock avoidance—deadlock-free routing and deadlock-free scheduling. The authors supply simple and complex industrial manufacturing system examples to illustrate time-tested concepts, theories, and approaches for solving real-life application problems. Written in a clear and concise manner, the text covers applications to automated and reconfigurable manufacturing systems, automated guided vehicle (AGV) systems, semiconductor manufacturing systems, and flexible assembly systems. Explaining complex concepts in a manner that is easy to understand, the authors provide the understanding and tools needed for more effective modeling, analysis, performance evaluation, control, and scheduling of engineering processes that will lead to more flexible and efficient manufacturing systems.

Modeling and Control of Precision Actuators explores new technologies that can ultimately be applied in a myriad of industries. It covers dynamical analysis of precise actuators and strategies of design for various control applications. The book addresses four main schemes: modeling and control of precise actuators; nonlinear control of precise actuators, including sliding mode control and neural network feedback control; fault detection and fault-tolerant control; and advanced air bearing control. It covers application issues in the modeling and control of precise actuators, providing several interesting case studies for more application-oriented readers. Introduces the driving forces behind precise actuators Describes nonlinear dynamics of precise actuators and their mathematical forms, including hysteresis, creep, friction, and force ripples Presents the control strategies for precise actuators based on Preisach model as well as creep dynamics Develops relay feedback techniques for identifying nonlinearities such as friction and force ripples Discusses a MPC approach based on piecewise affine models which emulate the frictional effects in the precise actuator Covers the concepts of air bearing stages with the corresponding control method Provides a set of schemes suitable for fault detection and accommodation control of mechanical systems Emphasizing design theory and control strategies, the book includes simulation and practical examples for each chapter; covers precise actuators such as piezo motors, coil motors, air bearing motors, and linear motors; discusses integration among different technologies; and includes three case studies in real projects. The book concludes by linking design methods and their applications, emphasizing the key issues involved and how to implement the precision motion control tasks in a practical system. It provides a concise and comprehensive source of the state-of-the-art developments and results for modeling and control of precise actuators.

This book reports on an outstanding research devoted to modeling and control of dynamic systems using fractional-order calculus. It describes the development of model-based control design methods for systems described by fractional dynamic models. More than 300 years had passed since Newton and Leibniz developed a set of mathematical tools we now know as calculus. Ever since then the idea of non-integer derivatives and integrals, universally referred to as fractional calculus, has been of interest to many researchers. However, due to various issues, the usage of fractional-order models in real-life applications was limited. Advances in modern computer science made it possible to apply efficient numerical methods to the computation of fractional derivatives and integrals. This book describes novel methods developed by the author for fractional modeling and control, together with their successful application in real-world process control scenarios.

This text offers a modern view of process control in the context of today's technology. It provides the standard material in a coherent presentation and uses a notation that is more consistent with the research literature in process control. Topics that are unique include a unified approach to model representations, process model formation and process identification, multivariable control, statistical quality control, and model-based control. This book is designed to be used as an introductory text for undergraduate courses in process dynamics and control. In addition to chemical engineering courses, the text would also be suitable for such courses taught in mechanical, nuclear, industrial, and metallurgical engineering departments. The material is organized so that modern concepts are presented to the student but details of the most advanced material are left to later chapters. The text material has been developed, refined, and classroom tested over the last 10-15 years at the University of Wisconsin and more recently at the University of Delaware. As part of the course at Wisconsin, a laboratory has been developed to allow the students hands-on experience with measurement instruments, real time computers, and experimental process dynamics and control problems.

**Modeling and Control in Air-conditioning Systems**

**Modeling and Control in Solid Mechanics**

**Modeling and Control of Drug Delivery Systems**

**Multiple Model Approaches To Nonlinear Modelling And Control**

**Modeling and Control of Precision Actuators**

*"The emerging fuel cell (FC) technology is growing rapidly in its applications from small-scale portable electronics to large-scale power generation. This book gives students, engineers, and scientists a solid understanding of the FC dynamic modeling and controller design to adapt FCs to particular applications in distributed power generation." "The book begins with a fascinating introduction to the subject, including a brief history of the U.S. electric utility formation and restructuring. Next, it provides coverage of power deregulation and distributed generation (DG), D<sub>6</sub> types, fuel cell DGs, and the hydrogen economy. Modeling and Control of Fuel Cells is an excellent reference book for students and professionals in electrical, chemical, and mechanical engineering and scientists working in the FC area."*-BOOK JACKET.

*This book investigates the latest modeling and control technologies in the context of air-conditioning systems. Firstly, it introduces the state-space method for developing dynamic models of all components in a central air-conditioning system. The models are primarily nonlinear and based on the fundamental principle of energy and mass conservation, and are transformed into state-space form through linearization. The book goes on to describe and discuss the state-space models with the help of graph theory and the structure-matrix theory. Subsequently, virtual sensor calibration and virtual sensing methods (which are very useful for real system control) are illustrated together with a case study. Model-based predictive control and state-space feedback control are applied to air-conditioning systems to yield better local control, while the air-side synergic control scheme and a global optimization strategy based on the decomposition-coordination method are developed so as to achieve energy conservation in the central air-conditioning system. Lastly, control strategies for VAV systems including total air volume control and trim & response static pressure control are investigated in practice.*

*Comprehension of complex systems comes from an understanding of not only the behavior of constituent elements but how they act together to form the behavior of the whole. However, given the multidisciplinary nature of complex systems, the scattering of information across different areas creates a chaotic situation for those trying to understand possible solutions and applications. Modeling and Control of Complex Systems brings together a number of research experts to present some of their latest approaches and future research directions in a language accessible to system theorists. Contributors discuss complex systems such as networks for modeling and control of civil structures, vehicles, robots, biomedical systems, fluid flow systems, and home automation systems. Each chapter provides theoretical and methodological descriptions of a specific application in the control of complex systems, including congestion control in computer networks, autonomous multi-robot docking systems, modeling and control in cancer genomics, and backstepping controllers for stabilization of turbulent flow PDEs. With this unique reference, you will discover how complexity is dealt with in different disciplines and learn about the latest methodologies, which are applicable to your own specialty. The balanced mix of theory and simulation presented by Modeling and Control of Complex Systems supplies a strong vehicle for enlarging your knowledge base a fueling future advances and incredible breakthroughs.*

*Craig Kluever 's Dynamic Systems: Modeling, Simulation, and Control highlights essential topics such as analysis, design, and control of physical engineering systems, often composed of interacting mechanical, electrical and fluid subsystem components. The major topics covered in this text include mathematical modeling, system-response analysis, and an introduction to feedback control systems. Dynamic Systems integrates an early introduction to numerical simulation using MATLAB's Simulink for integrated systems. Simulink® and MATLAB® tutorials for both software programs will also be provided. The author's text also has a strong emphasis on real-world case studies.*

*Process Dynamics, Modeling, and Control*

*Power System Modeling, Computation, and Control*

*Dynamic Modeling and Control of Engineering Systems*

*Modeling and Control of Antennas and Telescopes*

*Modeling and Electronic Management of Internal Combustion Engines*

Control systems have come to play an important role in the performance of modern vehicles with regards to meeting goals on low emissions and low fuel consumption. To achieve these goals, modeling, simulation, and analysis have become standard tools for the development of control systems in the automotive industry. Modeling and Control of Engines and Drivelines provides an up-to-date treatment of the topic from a clear perspective of systems engineering and control systems, which are at the core of vehicle design. This book has three main goals. The first is to provide a thorough understanding of component models as building blocks. It has therefore been important to provide measurements from real processes, to explain the underlying physics, to describe the modeling considerations, and to validate the resulting models experimentally. Second, the authors show how the models are used in the current design of control and diagnosis systems. These system designs are never used in isolation, so the third goal is to provide a complete setting for system integration and evaluation, including complete vehicle models together with actual requirements and driving cycle analysis. Key features: Covers signals, systems, and control in modern vehicles Covers the basic dynamics of internal combustion engines and drivelines Provides a set of standard models and includes examples and case studies Covers turbo- and super-charging, and automotive dependability and diagnosis Accompanied by a web site hosting example models and problems and solutions Modeling and Control of Engines and Drivelines is a comprehensive reference for graduate students and the authors' close collaboration with the automotive industry ensures that the knowledge and skills that practicing engineers need when analysing and developing new powertrain systems are also covered.

Modeling and Control of Power Electronics Converter Systems for Power Quality Improvements provides grounded theory for the modeling, analysis and control of different converter topologies that improve the power quality of mains. Intended for researchers and practitioners working in the field, topics include modeling equations and the state of research to improve power quality converters. By presenting control methods for different converter topologies and aspects related to multi-level inverters and specific analysis related to the AC interface of drives, the book helps users by putting a particular emphasis on different control algorithms that enhance knowledge and research work. Present In-depth coverage of modeling and control methods for different converter topology Includes a particular emphasis on different control algorithms to give readers an easier understanding Provides a results and discussion chapter and MATLAB simulation to support worked examples and real-life application scenarios

Offering a different approach to other textbooks in the area, this book is a comprehensive introduction to the subject divided in three broad parts. The first part deals with building physical models, the second part with developing empirical models and the final part discusses developing process control solutions. Theory is discussed where needed to ensure students have a full understanding of key techniques that are used to solve a modeling problem. **Hallmark Features:** Includes worked out examples of processes where the theory learned early on in the text can be applied. Uses MATLAB simulation examples of all processes and modeling techniques—further information on MATLAB can be obtained from [www.mathworks.com](http://www.mathworks.com) Includes supplementary website to include further references, worked examples and figures from the book This book is structured and aimed at upper level undergraduate students within chemical engineering and other engineering disciplines looking for a comprehensive introduction to the subject. It is also of use to practitioners of process control where the integrated approach of physical and empirical modeling is particularly valuable.

Open-channel hydraulics are described by hyperbolic equations, derived from laws of conservation of mass and momentum, called Saint-Venant equations. In conjunction with hydraulic structure equations these are used to represent the dynamic behavior of water flowing in rivers, irrigation canals, and sewers. Building on a detailed analysis of open-channel flow modeling, this monograph constructs control design methodologies based on a frequency domain approach. In practice, many open-channel systems are controlled with classical input-output controllers that are usually poorly tuned. The approach of this book, fashioning pragmatic engineering solutions for the control of open channels is given rigorous mathematical justification. Once the control objectives are clarified, a generic control design method is proposed, first for a canal pool, and then for a whole canal. The methods developed in the book have been validated on several canals of various dimensions up to a large scale irrigation canal.

Modeling and Control of Hydrosystems

Modeling and Control of Fuel Cells

Modeling and Control of Infectious Diseases in the Host

Fractional-order Modeling and Control of Dynamic Systems

Modeling and Control of Vibration in Mechanical Systems

Unifying the most important methodology in this field, Multi-Resolution Methods for Modeling and Control of Dynamical Systems explores existing approximation methods as well as develops new ones for the approximate solution of large-scale dynamical system problems. It brings together a wide set of material from classical orthogonal function approximation, neural network input-output approximation, finite element methods for distributed parameter systems, and various approximation methods employed in adaptive control and learning theory. With sufficient rigor and generality, the book promotes a qualitative understanding of the development of key ideas. It facilitates a deep appreciation of the important nuances and restrictions implicit in the algorithms that affect the validity of the results produced. The text features benchmark problems throughout to offer insights and illustrate some of the computational implications. The authors provide a framework for understanding the advantages, drawbacks, and application areas of existing and new algorithms for input-output approximation. They also present novel adaptive learning algorithms that can be adjusted in real time to the various parameters of unknown mathematical models.

The field of discrete event systems has emerged to provide a formal treatment of many of the man-made systems such as manufacturing systems, communication networks, automated traffic systems, database management systems, and computer systems that are event-driven, highly complex, and not amenable to the classical treatments based on differential or difference equations. Discrete event systems is a growing field that utilizes many interesting mathematical models and techniques. In this book we focus on a high level treatment of discrete event systems, where the order of events, rather than their occurrence times, is the principal concern. Such treatment is needed to guarantee that the system under study meets desired logical goals. In this framework, discrete event systems are modeled by formal languages or, equivalently, by state machines. The field of logical discrete event systems is an interdisciplinary field-it includes ideas from computer science, control theory, and operations research. Our goal is to bring together in one book the relevant techniques from these fields. This is the first book of this kind, and our hope is that it will be useful to professionals in the area of discrete event systems since most of the material presented has appeared previously only in journals. The book is also designed for a graduate level course on logical discrete event systems. It contains all the necessary background material in formal language theory and lattice theory.

The only prerequisite is some degree of "mathematical maturity". Internal combustion engines still have a potential for substantial improvements, particularly with regard to fuel efficiency and environmental compatibility. These goals can be achieved with help of control systems. Modeling and Control of Internal Combustion Engines (ICE) addresses these issues by offering an introduction to cost-effective model-based control system design for ICE. The primary emphasis is put on the ICE and its auxiliary devices. Mathematical models for these processes are developed in the text and selected feedforward and feedback control problems are discussed. The appendix contains a summary of the most important controller analysis and design methods, and a case study that analyzes a simplified idle-speed control problem. The book is written for students interested in the design of classical and novel ICE control systems.

Energy exchange is a major foundation of the dynamics of physical systems, and, hence, in the study of complex multi-domain systems, methodologies that explicitly describe the topology of energy exchanges are instrumental in structuring the modeling and the computation of the system's dynamics and its control. This book is the outcome of the European Project "Geoplex" (FP5 IST-2001-34166) that studied and extended such system modeling and control methodologies. This unique book starts from the basic concept of port-based modeling, and extends it to port-Hamiltonian systems. This generic paradigm is applied to various physical domains, showing its power and unifying flexibility for real multi-domain systems.

Marine Systems Identification, Modeling and Control

A Data-driven Subspace Approach

Modeling, Identification and Control of Robots

Fuzzy Modeling for Control

Modeling and Control of Power Electronics Converter System for Power Quality Improvements

The current literature on dynamic systems is quite comprehensive, and system theory's mathematical jargon can remain quite complicated. Thus, there is a need for a compendium of accessible research that involves the broad range of fields that dynamic systems can cover, including engineering, life sciences, and the environment, and which can connect researchers in these fields. The Handbook of Research on Modeling, Analysis, and Control of Complex Systems is a comprehensive reference book that describes the recent developments in a wide range of areas including the modeling, analysis, and control of dynamic systems, as well as explores related applications. The book acts as a forum for researchers seeking to understand the latest theory findings and software problem experiments. Covering topics that include chaotic maps, predictive modeling, random bit generation, and software bug prediction, this book is ideal for professionals, academicians, researchers, and students in the fields of electrical engineering, computer science, control engineering, robotics, power systems, and biomedical engineering.

Process Modelling for Control concentrates on the modelling steps underlying a successful control design, answering questions like: How should I carry out the identification of my process to obtain a good model? How can I assess the quality of a model before to using it in control design? How can I ensure that a controller will stabilise a real process well enough before implementation? What is the most efficient method of order reduction to simplify the implementation of high-order controllers? System identification, model/controller validation and order reduction are studied in a common framework. Detailed worked examples, representative of various industrial applications, are given. This monograph uses mathematics convenient to researchers interested in real applications and to practising engineers interested in control theory. It enables control engineers to improve their methods and provides academics and graduate students with an all-round view of recent results in modelling for control.

With increased environmental awareness and rising costs, manufacturers are investing in real time monitoring and control of dyeing to increase its efficiency and quality. This book reviews ways of automating the dyeing process as well as ways of understanding key processes in dyeing, including dye transport in fluid systems. This understanding is then used to create models to simulate the dyeing process which can then be used to develop appropriate measurement and control systems. Control of variables such as temperature, pH, conductivity and dye concentration can then be used to ensure a more consistent and cost-effective dyeing process. Reviews the dyeing process and dye house automation, and the factors that affect dyeing quality and common difficulties in the process. Explains the principles underlying the dyeing process and provides a thorough understanding of the mathematical models that can be used to approximate it. Discusses techniques for monitoring dyebaths and controlling the dyeing process.

This textbook is ideal for a course in engineering systems dynamics and controls. The work is a comprehensive treatment of the analysis of lumped parameter physical systems. Starting with a discussion of mathematical models in general, and ordinary differential equations, the book covers input/output and state space models, computer simulation and modeling methods and techniques in mechanical, electrical, thermal and fluid domains. Frequency domain methods, transfer functions and frequency response are covered in detail. The book concludes with a treatment of stability, feedback control (PID, lead-lag, root locus) and an introduction to discrete time systems. This new edition features many new and expanded sections on such topics as: solving stiff systems, operational amplifiers, electrohydraulic servovalves, using Matlab with transfer functions, using Matlab with frequency response, Matlab tutorial and an expanded Simulink tutorial. The work has 40% more end-of-chapter exercises and 30% more examples.

Modeling and Control of Engines and Drivelines

Dynamic Modeling, Predictive Control and Performance Monitoring

Process Modelling for Control

Modeling, Simulation, and Control

Dynamic Systems

*Rule-based fuzzy modeling has been recognised as a powerful technique for the modeling of partly-known nonlinear systems. Fuzzy models can effectively integrate information from different sources, such as physical laws, empirical models, measurements and heuristics. Application areas of fuzzy models include prediction, decision support, system analysis, control design, etc. Fuzzy Modeling for Control addresses fuzzy modeling from the systems and control engineering points of view. It focuses on the selection of appropriate model structures, on the acquisition of dynamic fuzzy models from process measurements (fuzzy identification), and on the design of nonlinear controllers based on fuzzy models. To automatically generate fuzzy models from measurements, a comprehensive methodology is developed which employs fuzzy clustering techniques to partition the available data into subsets characterized by locally linear behaviour. The relationships between the presented identification method and linear regression are exploited, allowing for the combination of fuzzy logic techniques with standard system identification tools. Attention is paid to the trade-off between the accuracy and transparency of the obtained fuzzy models. Control design based on a fuzzy model of a nonlinear dynamic process is addressed, using the concepts of model-based predictive control and internal model control with an inverted fuzzy model. To this end, methods to exactly invert specific types of fuzzy models are presented. In the context of predictive control, branch-and-bound optimization is applied. The main features of the presented techniques are illustrated by means of simple examples. In*

*addition, three real-world applications are described. Finally, software tools for building fuzzy models from measurements are available from the author.*

*Provides students with an understanding of the modeling and practice in power system stability analysis and control design, as well as the computational tools used by commercial vendors Bringing together wind, FACTS, HVDC, and several other modern elements, this book gives readers everything they need to know about power systems. It makes learning complex power system concepts, models, and dynamics simpler and more efficient while providing modern viewpoints of power system analysis. Power System Modeling, Computation, and Control provides students with a new and detailed analysis of voltage stability; a simple example illustrating the BCU method of transient stability analysis; and one of only a few derivations of the transient synchronous machine model. It offers a discussion on reactive power consumption of induction motors during start-up to illustrate the low-voltage phenomenon observed in urban load centers. Damping controller designs using power system stabilizer, HVDC systems, static var compensator, and thyristor-controlled series compensation are also examined. In addition, there are chapters covering flexible AC transmission Systems (FACTS)—including both thyristor and voltage-sourced converter technology—and wind turbine generation and modeling. Simplifies the learning of complex power system concepts, models, and dynamics Provides chapters on power flow solution, voltage stability, simulation methods, transient stability, small signal stability, synchronous machine models (steady-state and dynamic models), excitation systems, and power system stabilizer design Includes advanced analysis of voltage stability, voltage recovery during motor starts, FACTS and their operation, damping control design using various control equipment, wind turbine models, and control Contains numerous examples, tables, figures of block diagrams, MATLAB plots, and problems involving real systems Written by experienced educators whose previous books and papers are used extensively by the international scientific community Power System Modeling, Computation, and Control is an ideal textbook for graduate students of the subject, as well as for power system engineers and control design professionals.*

*New trends in free boundary problems and new mathematical tools together with broadening areas of applications have led to attempts at presenting the state of art of the field in a unified way. In this monograph we focus on formal models representing contact problems for elastic and elastoplastic plates and shells. New approaches open up new fields for research. For example, in crack theory a systematic treatment of mathematical modelling and optimization of problems with cracks is required. Similarly, sensitivity analysis of solutions to problems subjected to perturbations, which forms an important part of the problem solving process, is the source of many open questions. Two aspects of sensitivity analysis, namely the behaviour of solutions under deformations of the domain of integration and perturbations of surfaces seem to be particularly demanding in this context. On writing this book we aimed at providing the reader with a self-contained study of the mathematical modelling in mechanics. Much attention is given to modelling of typical constructions applied in many different areas. Plates and shallow shells which are widely used in the aerospace industry provide good exam ples. Allied optimization problems consist in finding the constructions which are of maximal strength (endurance) and satisfy some other requirements, ego weight limitations. Mathematical modelling of plates and shells always requires a reasonable compromise between two principal needs. One of them is the accuracy of the de scription of a physical phenomenon (as required by the principles of mechanics).*

*A discussion of challenges related to the modeling and control of greenhouse crop growth, this book presents state-of-the-art answers to those challenges. The authors model the subsystems involved in successful greenhouse control using different techniques and show how the models obtained can be exploited for simulation or control design; they suggest ideas for the development of physical and/or black-box models for this purpose. Strategies for the control of climate- and irrigation-related variables are brought forward. The uses of PID control and feedforward compensators, both widely used in commercial tools, are summarized. The benefits of advanced control techniques—event-based, robust, and predictive control, for example—are used to improve on the performance of those basic methods. A hierarchical control architecture is developed governed by a high-level multiobjective optimization approach rather than traditional constrained optimization and artificial intelligence techniques. Reference trajectories are found for diurnal and nocturnal temperatures (climate-related setpoints) and electrical conductivity (fertirrigation-related setpoints). The objectives are to maximize profit, fruit quality, and water-use efficiency, these being encouraged by current international rules. Illustrative practical results selected from those obtained in an industrial greenhouse during the last eight years are shown and described. The text of the book is complemented by the use of illustrations, tables and real examples which are helpful in understanding the material. Modeling and Control of Greenhouse Crop Growth will be of interest to industrial engineers, academic researchers and graduates from agricultural, chemical, and process-control backgrounds.*

*Engine Modeling and Control*

*Modeling and Control in the Biomedical Sciences*

*With MATLAB and R*

*Distributed Generation Applications*

*Modeling and Control of Greenhouse Crop Growth*

From the ox carts and pottery wheels the spacecrafts and disk drives, efficiency and quality has always been dependent on the engineer's ability to anticipate and control the effects of vibration. And while progress in negating the noise, wear, and inefficiency caused by vibrat Control of Vibration in Mechanical Systems answers the essential needs of practitioners in systems and control with the most comprehensive resource available on the subject. Written as a reference for those working in high precision systems, this uniquely accessible volume various characteristics and effects Offers a close-up look at mechanical actuation systems that are achieving remarkably high precision positioning performance Includes techniques for rejecting vibrations of different frequency ranges Covers the theoretical developments and enough that readers will be able to apply the techniques with the help of MATLAB® Details a wealth of practical working examples as well as a number of simulation and experimental results with comprehensive evaluations The modern world's ever-growing spectra of sophisti aeronautic systems, and manufacturing systems have little tolerance for unanticipated vibration of even the slightest magnitude. Accordingly, vibration control continues to draw intensive focus from top control engineers and modelers. This resource demonstrates the remarka gives today's researchers the technology that they need to build upon into the future. Chunling Du is currently researching modeling and advanced servo control of hard disk drives at the Data Storage Institute in Singapore. Lihua Xie is the Director of the Centre for Intelligent Technological University in Singapore.

Written by two of Europe's leading robotics experts, this book provides the tools for a unified approach to the modelling of robotic manipulators, whatever their mechanical structure. No other publication covers the three fundamental issues of robotics: modelling, identification mathematical models required for the control and simulation of robots. · World class authority · Unique range of coverage not available in any other book · Provides a complete course on robotic control at an undergraduate and graduate level

Modeling and Control of Infectious Diseases in the Host: With MATLAB and R provides a holistic understanding of health and disease by presenting topics on quantitative decision-making that influence the development of drugs. The book presents modeling advances in different of key players, along with their respective interactions. By combining tailored in vivo experiments and mathematical modeling approaches, the book clarifies the relative contributions of different underlying mechanisms within hosts of the most lethal viral infections, including HIV parameter fitting, modeling and control applications are explained using MATLAB and R. Provides a multi-scale framework to link within-host infection dynamics (individual level) to between-host transmission fitness (epidemiological level) in viral infectious diseases Includes PK/P

Improve efficiency and decision-making at preclinical development phases Presents a theoretic approach to schedule drug treatments

Mechanical engineering, and engineering discipline born of the needs of the industrial revolution, is once again asked to do its substantial share in the call for industrial renewal. The general call is urgent as we face profound issues of productivity and competitiveness that requ

Mechanical Engineering Series is a series featuring graduate texts and research monographs intended to address the need for information in contemporary areas of mechanical engineering. The series is conceived as a comprehensive one that covers a broad range of c- centrat education and research. We are fortunate to have a distinguished roster of series editors, each an expert in one of the areas of concentration. The names of the series editors are listed on page vi of this volume. The areas of concentration are applied mechanics, biomechanics

control, energetics, mechanics of materials, processing, thermal science, and tribology. Preface This book is based on my experience with the control systems of antennas and radiotelesopes. Overwhelmingly, it is based on experience with the NASA Deep Space Network (DSN) developing control algorithms, eld testing, system identi cation, performance evaluation, and 1 troubleshooting. My previous book emphasized the theoretical aspects of antenna control engineering, while this one describes the application part of the antenna control engineering

Fuzzy Modelling and Fuzzy Control

Modelling, Simulation and Control of the Dyeing Process

Modelling and Control of Complex Systems

The Port-Hamiltonian Approach

Bridging Rigorous Theory and Advanced Technology

*These notes are based on (i) a series of lectures that I gave at the 14th Biennial Seminar of the Canadian Mathematical Congress held at the University of Western Ontario August 12-24, 1973 and (ii) some of my lectures in a modeling course that I have cotaught in the Division of Bio-Medical Sciences at Brown during the past several years. An earlier version of these notes appeared in the Center for Dynamical Systems Lectures Notes series (CDS LN 73-1, November 1973). I have in this revised and extended version of those earlier notes incorporated a number of changes based both on classroom experience and on my research efforts with several colleagues during the intervening period. The narrow viewpoint of the present notes (use of optimization and control theory in biomedical problems) reflects more the scope of the CMC lectures given in August, 1973 than the scope of my own interests. Indeed, my real interests have included the modeling process itself as well as the contributions made by investiga tors who employ the techniques and ideas of control theory, systems analysis, dif ferential equations, and stochastic processes. Some of these contributions have quite naturally involved application of optimal control theory. But in my opinion many of the interesting efforts being made in modeling in the biomedical sciences encompass much more than the use of control theory.*

*This book aims to provide a unified treatment of input/output modelling and of control for discrete-time dynamical systems subject to random disturbances. The results presented are of wide applica bility in control engineering, operations research, econometric modelling and many other areas. There are two distinct approaches to mathematical modelling of physical systems: a direct analysis of the physical mechanisms that comprise the process, or a 'black box' approach based on analysis of input/output data. The second approach is adopted here, although of course the properties ofthe models we study, which within the limits of linearity are very general, are also relevant to the behaviour of systems represented by such models, however they are arrived at. The type of system we are interested in is a discrete-time or sampled-data system where the relation between input and output is (at least approximately) linear and where additive random dis turbances are also present, so that the behaviour of the system must be investigated by statistical methods. After a preliminary chapter summarizing elements of probability and linear system theory, we introduce in Chapter 2 some general linear stochastic models, both in input/output and state-space form. Chapter 3 concerns filtering theory: estimation of the state of a dynamical system from noisy observations. As well as being an important topic in its own right, filtering theory provides the link, via the so-called innovations representation, between input/output models (as identified by data analysis) and state-space models, as required for much contemporary control theory.*

*In the last ten years, a true explosion of investigations into fuzzy modeling and its applications in control, diagnostics, decision making, optimization, pattern recognition, robotics, etc. has been observed. The attraction of fuzzy modeling results from its intelligibility and the high effectiveness of the models obtained. Owing to this the modeling can be applied for the solution of problems which could not be solved till now with any known conventional methods. The book provides the reader with an advanced introduction to the problems of fuzzy modeling and to one of its most important applications: fuzzy control. It is based on the latest and most significant knowledge of the subject and can be used not only by control specialists but also by specialists working in any field requiring plant modeling, process modeling, and systems modeling, e.g. economics, business, medicine, agriculture, and meteorology.*

*This work presents approaches to modelling and control problems arising from conditions of ever increasing nonlinearity and complexity. It prescribes an approach that covers a wide range of methods being combined to provide multiple model solutions. Many component methods are described, as well as discussion of the strategies available for building a successful multiple model approach.*

*Introduction to Modeling and Control of Internal Combustion Engine Systems*

*Modeling for Control and Prediction*

*Fuzzy Modeling and Control*

*Model-Based Control:*

*Efficient Modeling and Control of Large-Scale Systems*

Marine Systems Identification, Modeling and Control is a concise, stand-alone resource covering the theory and practice of dynamic systems and control for marine engineering students and professionals. Developed from a distance learning CPD course on marine control taught by the authors, the book presents the essentials of the subject, including system representation and transfer, feedback control and closed loop stability. Simulation code and worked examples are provided for both Scilab and MATLAB, making it suitable for both those without access to expensive software and those using MATLAB in a professional setting. This title considers the key topics without superfluous detail and is illustrated with marine industry examples. Concise and practical, covering the relevant theory without excessive detail Industry-specific examples and applications for marine engineering students and professionals Clearly presents key topics of the subject, including system representation and transfer, feedback control and closed loop stability, making it ideal for self-study or reference Simulation code and worked examples using Scilab and MATLAB provided on the book's companion website

Complexity and dynamic order of controlled engineering systems is constantly increasing. Complex large scale systems (where "large" reflects the system's order and not necessarily its physical size) appear in many engineering fields, such as micro-electromechanics, manufacturing, aerospace, civil engineering and power engineering. Modeling of these systems often result in very high-order models imposing great challenges to the analysis, design and control problems. "Efficient Modeling and Control of Large-Scale Systems" compiles state-of-the-art contributions on recent analytical and computational methods for addressing model reduction, performance analysis and feedback control design for such systems. Also addressed at length are new theoretical developments, novel computational approaches and illustrative applications to various fields, along with: · An interdisciplinary focus emphasizing methods and approaches that can be commonly applied in various engineering fields · Examinations of applications in various fields including micro-electromechanical systems (MEMS), manufacturing processes, power networks, traffic control "Efficient Modeling and Control of Large-Scale Systems" is an ideal volume for engineers and researchers working in the fields of control and dynamic systems.

A typical design procedure for model predictive control or control performance monitoring consists of: 1. identification of a parametric or nonparametric model; 2. derivation of the output predictor from the model; 3. design of the control law or calculation of performance indices according to the predictor. Both design problems need an explicit model form and both require this three-step design procedure. Can this design procedure be simplified? Can an explicit model be avoided? With these questions in mind, the authors eliminate the first and second step of the above design procedure, a "data-driven" approach in the sense that no traditional parametric models are used; hence, the intermediate subspace matrices, which are obtained from the process data and otherwise identified as a first step in the subspace identification methods, are used directly for the designs. Without using an explicit model, the design procedure is simplified and the modelling error caused by parameterization is eliminated.

Model-Based Control will be a collection of state-of-the-art contributions in the field of modelling, identification, robust control and optimization of dynamical systems, with particular attention to the application domains of motion control systems (high-accuracy positioning systems) and large scale industrial process control systems. The book will be directed to academic and industrial people involved in research in systems and control, industrial process control and mechatronics.

A Unified Framework Using Standard Black-box Techniques

Modeling and Control of Complex Physical Systems

Multi-Resolution Methods for Modeling and Control of Dynamical Systems

System Modeling and Control with Resource-Oriented Petri Nets

Handbook of Research on Modeling, Analysis, and Control of Complex Systems

**Fuzzy logic methodology has proven effective in dealing with complex nonlinear systems containing uncertainties that are otherwise difficult to model. Technology based on this methodology is applicable to many real-world problems, especially in the area of consumer products. This book presents the first comprehensive, unified treatment of fuzzy modeling and fuzzy control, providing tools for the control of complex nonlinear systems. Coverage includes model complexity, model precision, and computing time. This is an excellent reference for electrical, computer, chemical, industrial, civil, manufacturing, mechanical and aeronautical engineers, and also useful for graduate courses in electrical engineering, computer engineering, and computer science.**

**The increasing demands for internal combustion engines with regard to fuel consumption, emissions and driveability lead to more actuators, sensors and complex control functions. A systematic implementation of the electronic control systems requires mathematical models from basic design through simulation to calibration. The book treats physically-based as well as models based experimentally on test benches for gasoline (spark ignition) and diesel (compression ignition) engines and uses them for the design of the different control functions. The main topics are: - Development steps for engine control - Stationary and dynamic experimental modeling - Physical models of intake, combustion, mechanical system, turbocharger, exhaust, cooling, lubrication, drive train - Engine control structures, hardware, software, actuators, sensors, fuel supply, injection system, camshaft - Engine control methods, static and dynamic feedforward and feedback control, calibration and optimization, HiL, RCP, control software development - Control of gasoline engines, control of air/fuel, ignition, knock, idle, coolant, adaptive control functions - Control of diesel engines, combustion models, air flow and exhaust recirculation control, combustion-pressure-based control (HCCI), optimization of feedforward and feedback control, smoke limitation and emission control This book is an introduction to electronic engine management with many practical examples, measurements and research results. It is aimed at advanced students of electrical, mechanical, mechatronic and control engineering and at practicing engineers in the field of combustion engine and automotive engineering.**

**This compact and original reference and textbook presents the most important classical and modern essentials of control engineering in a single volume. It constitutes a harmonic mixture of control theory and applications, which makes the book especially useful for students, practicing engineers and researchers interested in modeling and control of processes. Well written and easily understandable, it includes a range of methods for the analysis and design of control systems.**

**Modeling and Control of Drug Delivery Systems provides comprehensive coverage of various drug delivery and targeting systems and their state-of-the-art related works, ranging from theory to real-world deployment and future perspectives. Various drug delivery and targeting systems have been developed to minimize drug degradation and adverse effect and increase drug bioavailability. Site-specific drug delivery may be either an active and/or passive process. Improving delivery techniques that minimize toxicity and increase efficacy offer significant potential benefits to patients and open up new markets for pharmaceutical companies. This book will attract many researchers working in DDS field as it provides an essential source of information for pharmaceutical scientists and pharmacologists working in academia as well as in the industry. In addition, it has useful information for pharmaceutical physicians and scientists in many disciplines involved in developing DDS, such as chemical engineering, biomedical engineering, protein engineering, gene therapy.**

**Presents some of the latest innovations of approaches to DDS from dynamic controlled drug delivery, modeling, system analysis, optimization, control and monitoring Provides a unique, recent and comprehensive reference on DDS with the focus on cutting-edge technologies and the latest research trends in the area Covers the most recent works, in particular, the challenging areas related to modeling and control techniques applied to DDS**

**Stochastic Modelling and Control**

**Modeling and Control of Logical Discrete Event Systems**

**Process Modelling, Identification, and Control**

**Process Dynamics and Control**