

Nonlinear Control Systems And Power System Dynamics The International Series On Asian Studies In Computer And Information Science

A systematic computer-aided approach provides a versatile setting for the control engineer to overcome the complications of controller design for highly nonlinear systems. Computer-aided Nonlinear Control System Design provides such an approach based on the use of describing functions. The text deals with a large class of nonlinear systems without restrictions on the system order, the number of inputs and/or outputs or the number, type or arrangement of nonlinear terms. The strongly software-oriented methods detailed facilitate fulfillment of tight performance requirements and help the designer to think in purely nonlinear terms, avoiding the expedient of linearization which can impose substantial and unrealistic model limitations and drive up the cost of the final product. Design procedures are presented in a step-by-step algorithmic format each step being a functional unit with outputs that drive the other steps. This procedure may be easily implemented on a digital computer with example problems from mechatronic and aerospace design being used to demonstrate the techniques discussed. The author's commercial MATLAB®-based environment, available separately from insert URL here, can be used to create simulations showing the results of using the computer-aided control system design ideas characterized in the text. Academic researchers and graduate students studying nonlinear control systems and control engineers dealing with nonlinear plant, particularly mechatronic or aerospace systems will find Computer-aided Nonlinear Control System Design to be of great practical assistance adding to their toolbox of techniques for dealing with system nonlinearities. A basic knowledge of calculus, nonlinear analysis and software engineering will enable the reader to get the best from this book.

Backstepping Control of Nonlinear Dynamical Systems addresses both the fundamentals of backstepping control and advances in the field. The latest techniques explored include 'active backstepping control', 'adaptive backstepping control', 'fuzzy backstepping control' and 'adaptive fuzzy backstepping control'. The reference book provides numerous simulations using MATLAB and circuit design. These illustrate the main results of theory and applications of backstepping control of nonlinear control systems. Backstepping control encompasses varied aspects of mechanical engineering and has many different applications within the field. For example, the book covers aspects related to robot manipulators, aircraft flight control systems, power systems, mechanical systems, biological systems and chaotic systems. This multifaceted view of subject areas means that this useful reference resource will be ideal for a large cross section of the mechanical engineering community. Details the real-world applications of backstepping control Gives an up-to-date insight into the theory, uses and application of backstepping control Bridges the gaps for different fields of engineering, including mechanical engineering, aeronautical engineering, electrical engineering, communications engineering, robotics and biomedical instrumentation

This book presents a study on the novel concept of "event-triggered control of nonlinear systems subject to disturbances", discussing the theory and practical applications. Richly illustrated, it is a valuable resource for researchers, engineers and graduate students in automation engineering who wish to learn the theories, technologies, and applications of event-triggered control of nonlinear systems.

Significant progress has been made on nonlinear control systems in the past two decades. However, many of the existing nonlinear control methods cannot be readily used to cope with communication and networking issues without nontrivial modifications. For example, small quantization errors may cause the performance of a "well-designed" nonlinear control system to deteriorate. Motivated by the need for new tools to solve complex problems resulting from smart power grids, biological processes, distributed computing networks, transportation networks, robotic systems, and other cutting-edge control applications, Nonlinear Control of Dynamic Networks tackles newly arising theoretical and real-world challenges for stability analysis and control design, including nonlinearity, dimensionality, uncertainty, and information constraints as well as behaviors stemming from quantization, data-sampling, and impulses. Delivering a systematic review of the nonlinear small-gain theorems, the text: Supplies novel cyclic-small-gain theorems for large-scale nonlinear dynamic networks Offers a cyclic-small-gain framework for nonlinear control with static or dynamic quantization Contains a combination of cyclic-small-gain and set-valued map designs for robust control of nonlinear uncertain systems subject to sensor noise Presents a cyclic-small-gain result in directed graphs and distributed control of nonlinear multi-agent systems with fixed or dynamically changing topology Based on the authors' recent research, Nonlinear Control of Dynamic Networks provides a unified framework for robust, quantized, and distributed control under information constraints. Suggesting avenues for further exploration, the book encourages readers to take into consideration more communication and networking issues in control designs to better handle the arising challenges.

Nonlinear Control Systems and Power System Dynamics

Selected papers from the 2nd IFAC Symposium, Bordeaux, France, 24 - 26 June 1992

Nonlinear Phenomena in Power Electronics

Applications to Electromechanical Systems

Nonlinear Control Engineering

Nonlinear Control Systems Design 1989

Brings the knowledge of 24 experts in this maturing field out from the narrow confines of academic circles, and makes it accessible to graduate students and power electronics professionals alike. * Provides practicing engineers with the knowledge to predict power requirement behavior. * The insights gained from this all-inclusive compilation will ultimately lead to better design methodologies.

The development of computer software for nonlinear control systems has provided many benefits for teaching, research, and the development of control systems design. MATLAB is considered the dominant software platforms for linear and nonlinear control systems analysis. This book provides an easy way to learn nonlinear control systems such as feedback linearization technique and Sliding mode control (Structure variable control) which are one of the most used techniques in nonlinear control dynamical systems; therefore teachers-students and researchers are all in need to handle such techniques; and since they are too difficult for them to handle such nonlinear controllers especially for a more complicated systems such as induction motor, satellite, and vehicles dynamical models. Thus, this document it is an excellent resource for learning the principle of feedback linearization and sliding mode techniques in an easy and simple way: Provides a briefs description of the feedback linearization and sliding mode control strategies Includes a simple method on how to determine the right and appropriate controller (P-PI-PID) for feedback linearization control strategy. A Symbolic MATLAB Based function for finding the feedback linearization and sliding mode controllers are developed and tested using several examples. A simple method for finding the approximate sliding mode controller parameters is introduced where the program used to construct the nonlinear controller uses symbolic computations; such that the user should provide the program with the necessary functions f(x), g(x) and h(x) using the symbolic library.

When M. Vidyasagar wrote the first edition of Nonlinear Systems Analysis, most control theorists considered the subject of nonlinear systems a mystery. Since then, advances in the application of differential geometric methods to nonlinear analysis have matured to a stage where every control theorist needs to possess knowledge of the basic techniques because virtually all physical systems are nonlinear in nature. The second edition, now republished in SIAM's Classics in Applied Mathematics series, provides a rigorous mathematical analysis of the behavior of nonlinear control systems under a variety of situations. It develops nonlinear generalizations of a large number of techniques and methods widely used in linear control theory. The book contains three extensive chapters devoted to the key topics of Lyapunov stability, input-output stability, and the treatment of differential geometric control theory. Audience: this text is designed for use at the graduate level in the area of nonlinear systems and as a resource for professional researchers and practitioners working in areas such as robotics, spacecraft control, motor control, and power systems.

In this book, modeling and control design of electric motors, namely step motors, brushless DC motors and induction motors, are considered. The book focuses on recent advances on feedback control designs for various types of electric motors, with a slight emphasis on stepper motors. For this purpose, the authors explore modeling of these devices to the extent needed to provide a high-performance controller, but at the same time one amenable to model-based nonlinear designs. The control designs focus primarily on recent robust adaptive nonlinear controllers to attain high performance. It is shown that the adaptive robust nonlinear controller on its own achieves reasonably good performance without requiring the exact knowledge of motor parameters. While carefully tuned classical controllers often achieve required performance in many applications, it is hoped that the advocated robust and adaptive designs will lead to standard universal controllers with minimal need for fine tuning of control parameters.

Advances and Applications in Nonlinear Control Systems

Second Edition

Using Describing Function Models

Nonlinear and Optimal Control Systems

Backstepping Control of Nonlinear Dynamical Systems

Utilizing Exergy, Entropy, Static and Dynamic Stability, and Lyapunov Analysis

This monograph presents recent advances in differential flatness theory and analyzes its use for nonlinear control and estimation. It shows how differential flatness theory can provide solutions to complicated control problems, such as those appearing in highly nonlinear multivariable systems and distributed-parameter systems. Furthermore, it shows that differential flatness theory makes it possible to perform filtering and state estimation for a wide class of nonlinear dynamical systems and provides several descriptive test cases. The book focuses on the design of nonlinear adaptive controllers and nonlinear filters, using exact linearization based on differential flatness theory. The adaptive controllers obtained can be applied to a wide class of nonlinear systems with unknown dynamics, and assure reliable functioning of the control loop under uncertainty and varying operating conditions. The filters obtained outperform other nonlinear filters in terms of accuracy of estimation and computation speed. The book presents a series of application examples to confirm the efficiency of the proposed nonlinear filtering and adaptive control schemes for various electromechanical systems. These include: · industrial robots; · mobile robots and autonomous vehicles; · electric power generation; · electric motors and actuators; · power electronics; · internal combustion engines; · distributed-parameter systems; and · communication systems. Differential Flatness Approaches to Nonlinear Control and Filtering will be a useful reference for academic researchers studying advanced problems in nonlinear control and nonlinear dynamics, and for engineers working on control applications in electromechanical systems.

In the last two decades, the development of specific methodologies for the control of systems described by nonlinear mathematical models has attracted an ever increasing interest. New breakthroughs have occurred which have aided the design of nonlinear control systems. However there are still limitations which must be understood, some of which were addressed at the IFAC Symposium in Capri. The emphasis was on the methodological developments, although a number of the papers were concerned with the presentation of applications of nonlinear design philosophies to actual control problems in chemical, electrical and mechanical engineering.

Discrete-Time Inverse Optimal Control for Nonlinear Systems proposes a novel inverse optimal control scheme for stabilization and trajectory tracking of discrete-time nonlinear systems. This avoids the need to solve the associated Hamilton-Jacobi-Bellman equation and minimizes a cost functional, resulting in a more efficient controller. Design More Efficient Controllers for Stabilization and Trajectory Tracking of Discrete-Time Nonlinear Systems The book presents two approaches for controller synthesis: the first based on passivity theory and the second on a control Lyapunov function (CLF). The synthesized discrete-time optimal controller can be directly implemented in real-time systems. The book also proposes the use of recurrent neural networks to model discrete-time nonlinear systems. Combined with the inverse optimal control approach, such models constitute a powerful tool to deal with uncertainties such as unmodeled dynamics and disturbances. Learn from Simulations and an In-Depth Case Study The authors include a variety of simulations to illustrate the effectiveness of the synthesized controllers for stabilization and trajectory tracking of discrete-time nonlinear systems. An in-depth case study applies the control schemes to glycemic control in patients with type 1 diabetes mellitus, to calculate the adequate insulin delivery rate required to prevent hyperglycemia and hypoglycemia levels. The discrete-time optimal and robust control techniques proposed can be used in a range of industrial applications, from aerospace and energy to biomedical and electromechanical systems. Highlighting optimal and efficient control algorithms, this is a valuable resource for researchers, engineers, and students working in nonlinear system control.

The book's text focuses on explaining and analyzing the dynamic performance of linear and nonlinear systems, in particular for Power Systems (PS) including Hybrid Power Sources (HPS). The system stability is important for both PS operation and planning. Placing emphasis on understanding the underlying stability principles, the book opens with an exploration of basic concepts using mathematical models and case studies from linear and nonlinear system, and continues with complex models and algorithms from field of PS. The book's features include: (1) progressive approach from simplicity to complexity, (2) deeper look into advanced aspects of stability theory, (3) detailed description of system stability using state space energy conservation principle, (4) review of some research in the field of PS stability analysis, (5) advanced models and algorithms for Transmission Network Expansion Planning (TNEP), (6) Stability enhancement including the use of Power System Stabilizer (PSS) and Flexible Alternative Current Transmission Systems (FACTS), and (7) examination of the influence of nonlinear control on fuel cell HPS dynamics. The book will be easy to read and understand and will be an essential resource for both undergraduate and graduate students in electrical engineering as well as to the PhDs and engineers from this field. It is also a clear and comprehensive reference text for undergraduate students, postgraduate and research students studying power systems, and also for practicing engineers and researchers who are working in electricity companies or in the development of power system technologies. All will appreciate the authors' accessible approach in introduction the power system dynamics and stability from both a mathematical and engineering viewpoint.

A Lyapunov-Based Approach

Bifurcations, Chaos, Control, and Applications

Analysis and Design

Soft-Computing-Based Nonlinear Control Systems Design

PID Passivity-Based Control of Nonlinear Systems with Applications

Nonlinear Control Applied to Power Systems

When large disturbances occur in interconnected power systems, there exists the danger that the power system states may leave an associated region of stability, if timely corrective action is not taken. Open-loop remedial control actions such as field-forcing, line-tripping, switching of series-capacitors, energizing braking resistors, etc., are helpful in reducing the effects of the disturbance, but do not guarantee that the post-fault power system will be stabilized. Linear controllers are widely used in the power industry, and provide excellent damping when the power system state is close to the equilibrium. In general, they provide conservative regions of stability. This study focuses on the development of nonlinear controllers to enhance the stability of interconnected power systems following large disturbances, and allow stable operation at high power levels. There is currently interest in the power industry in using thyristor-controlled series-capacitors for the dual purpose of exercising tighter control on steady-state power flows and enhancing system stability. This device is used to implement the nonlinear controller in this dissertation. A mathematical model of the power system controlled by the thyristor-controlled series-capacitor is developed for the purpose of controller design. Discrete-time, nonlinear predictive controllers are derived by minimizing criterion functions that are quadratic in the output variables over a finite-horizon of interest, with respect to the control variables. The control policies developed in this manner are centralized in nature. The stabilizing effect of such controllers is discussed. A potential drawback is the need to have large prediction horizons to assure stability. In this context, a coordinated-control policy is proposed, in which the nonlinear predictive controller is designed with a small prediction horizon. For a class of disturbances, such nonlinear predictive controllers return the power system state to a small neighborhood of the post-fault equilibrium, where linear controllers provide asymptotic stabilization and rapid damping. Methods of coordinating the controllers are discussed. Simulation results are provided on a sample four-machine power system model. There exists considerable uncertainty in power system models due to constantly shifting loads and generations, line-switching following disturbances, etc. The performance of fixed-parameter controllers may not be good when the plant description changes considerably from the reference. In this context, a bilinear model-based self-tuning controller is proposed for the stabilization of power systems for a class of faults. A class of generic predictive controllers are presented for use with the self-tuning controller. Simulation results on single-machine and multimachine power systems are provided.

This text emphasizes classical methods and presents essential analytical tools and strategies for the construction and development of improved design methods in nonlinear control. It offers engineering procedures for the frequency domain, as well as solved examples for clear understanding of control applications in the industrial, electrical, proce

This book presents an innovative control system design process motivated by renewable energy electric grid integration problems. The concepts developed result from the convergence of research and development goals which have important concepts in common: exergy flow, limit cycles, and balance between competing power flows. A unique set of criteria is proposed to design controllers for a class of nonlinear systems. A combination of thermodynamics with Hamiltonian systems provides the theoretical foundation which is then realized in a series of connected case studies. It allows the process of control design to be viewed as a power flow control problem, balancing the power flowing into a system against that being dissipated within it and dependent on the power being stored in it - an interplay between kinetic and potential energies. Human factors and the sustainability of self-organizing systems are dealt with as advanced topics.

In this work we derive asymptotically stabilizing control laws for electrical power systems using two nonlinear control synthesis techniques. For this transient stabilization problem the actuator considered is a power electronic device, a controllable series capacitor (CSC). The power system is described using two different nonlinear models - the second order swing equation and the third order flux-decay model. To start with, the CSC is modeled by the injection model which is based on the assumption that the CSC dynamics is very fast as compared to the dynamics of the power system and hence can be approximated by an algebraic equation. Here, by neglecting the CSC dynamics, the input vector $g(x)$ in the open loop system takes a complex form - the injection model. Using this model, interconnection and damping assignment passivity-based control (IDA-PBC) methodology is demonstrated on two power systems: a single machine infinite bus (SMIB) system and a two machine system. Further, IDA-PBC is used to derive stabilizing controllers for power systems, where the CSC dynamics are included as a first order system. Next, we consider a different control methodology, immersion and invariance (I&I), to synthesize an asymptotically stabilizing control law for the SMIB system with a CSC. The CSC is described by a first order system. As a generalization of I&I, we incorporate the power balance algebraic constraints in the load bus to the SMIB swing equation, and extend the design philosophy to a class of differential algebraic systems. The proposed result is then demonstrated on another example: a two-machine system with two load buses and a CSC. The controller performances are validated through simulations for all cases.

Nonlinear Dynamical Systems and Control

Nonlinear Control Design for Stressed Power Systems Using Normal Forms of Vector Fields

Modeling and Adaptive Nonlinear Control of Electric Motors

Analysis, Stability, and Control

Lagrangian and Hamiltonian Methods For Nonlinear Control 2006

Adaptive Learning Methods for Nonlinear System Modeling presents some of the recent advances on adaptive algorithms and machine learning methods designed for nonlinear system modeling and identification. Real-life problems always entail a certain degree of nonlinearity, which makes linear models a non-optimal choice. This book mainly focuses on those methodologies for nonlinear modeling that involve any adaptive learning approaches to process data coming from an unknown nonlinear system. By learning from available data, such methods aim at estimating the nonlinearity introduced by the unknown system. In particular, the methods presented in this book are based on online learning approaches, which process the data example-by-example and allow to model even complex nonlinearities, e.g., showing time-varying and dynamic behaviors. Possible fields of applications of such algorithms includes distributed sensor networks, wireless communications, channel identification, predictive maintenance, wind prediction, network security, vehicular networks, active noise control, information forensics and security, tracking control in mobile robots, power systems, and nonlinear modeling in big data, among many others. This book serves as a crucial resource for researchers, PhD and post-graduate students working in the areas of machine learning, signal processing, adaptive filtering, nonlinear control, system identification, cooperative systems, computational intelligence. This book may be also of interest to the industry market and practitioners working with a wide variety of nonlinear systems. Presents the key trends and future perspectives in the field of nonlinear signal processing and adaptive learning. Introduces novel solutions and improvements over the state-of-the-art methods in the very exciting area of online and adaptive nonlinear

identification. Helps readers understand important methods that are effective in nonlinear system modelling, suggesting the right methodology to address particular issues.

In this work, the authors present a global perspective on the methods available for analysis and design of non-linear control systems and detail specific applications. They provide a tutorial exposition of the major non-linear systems analysis techniques followed by a discussion of available non-linear design methods.

The book reports on the latest advances and applications of nonlinear control systems. It consists of 30 contributed chapters by subject experts who are specialized in the various topics addressed in this book. The special chapters have been brought out in the broad areas of nonlinear control systems such as robotics, nonlinear circuits, power systems, memristors, underwater vehicles, chemical processes, observer design, output regulation, backstepping control, sliding mode control, time-delayed control, variables structure control, robust adaptive control, fuzzy logic control, chaos, hyperchaos, jerk systems, hyperjerk systems, chaos control, chaos synchronization, etc. Special importance was given to chapters offering practical solutions, modeling and novel control methods for the recent research problems in nonlinear control systems. This book will serve as a reference book for graduate students and researchers with a basic knowledge of electrical and control systems engineering. The resulting design procedures on the nonlinear control systems are emphasized using MATLAB software.

Nonlinear Dynamical Systems and Control presents and develops an extensive treatment of stability analysis and control design of nonlinear dynamical systems, with an emphasis on Lyapunov-based methods. Dynamical system theory lies at the heart of mathematical sciences and engineering. The application of dynamical systems has crossed interdisciplinary boundaries from chemistry to biochemistry to chemical kinetics, from medicine to biology to population genetics, from economics to sociology to psychology, and from physics to mechanics to engineering. The increasingly complex nature of engineering systems requiring feedback control to obtain a desired system behavior also gives rise to dynamical systems. Wassim Haddad and VijaySekhar Chellaboina provide an exhaustive treatment of nonlinear systems theory and control using the highest standards of exposition and rigor. This graduate-level textbook goes well beyond standard treatments by developing Lyapunov stability theory, partial stability, boundedness, input-to-state stability, input-output stability, finite-time stability, semistability, stability of sets and periodic orbits, and stability theorems via vector Lyapunov functions. A complete and thorough treatment of dissipativity theory, absolute stability theory, stability of feedback systems, optimal control, disturbance rejection control, and robust control for nonlinear dynamical systems is also given. This book is an indispensable resource for applied mathematicians, dynamical systems theorists, control theorists, and engineers.

Power System Dynamics and Control

Applied Nonlinear Control

Nonlinear Control Systems

Design of Nonlinear Control Systems with the Highest Derivative in Feedback

Advanced Nonlinear Control of Complex Power Systems

Nonlinear Control Systems using MATLAB®

Over the last 50 years or so, a number of textbooks, monographs and even popular books have been published on nonlinear control theory and design methods. In the area of classical control, for example, there exist books concerned with phase-plane analysis, describing function approach, absolute stability and so on. In the area of modern control there are those related to optimal control, using differential geometry and the differential algebra method, variable structural control, H-infinite control and so on. These books have been useful in promoting the development of automatic control science and technology. Since 1990 there have been many new results and contributions in the area of nonlinear control. This book introduces those topics to interested readers. It will also benefit automation engineers, researchers and scholars in related fields. Contents:Generalized Hamiltonian Systems (D Cheng)Continuous Finite-Time Control (T P Leung & Y Hong)Local Stabilization of Nonlinear Systems by Dynamic Output Feedback (P Chen & H Qin)Hybrid Control for Global Stabilization of a Class of Systems (J Zhao)Robust and Adaptive Control of Nonholonomic Mechanical Systems with Applications to Mobile Robots (Y M Hu & W Huo)Introduction to Chaos Control and Anti-Control (G Chen et al.) Readership: Graduate students, researchers, designers of nonlinear control systems and controllers, and readers interested in the recent contributions to nonlinear control theory. Keywords:

Explore the foundational and advanced subjects associated with proportional-integral-derivative controllers from leading authors in the field In PID Passivity-Based Control of Nonlinear Systems with Applications, expert researchers and authors Drs. Romeo Ortega, Jose Guadalupe Romero, Pablo Borja, and Alejandro Donaire deliver a comprehensive and detailed discussion of the most crucial and relevant concepts in the analysis and design of proportional-integral-derivative controllers using passivity techniques. The accomplished authors present a formal treatment of the recent research in the area and offer readers practical applications of the developed methods to physical systems, including electrical, mechanical, electromechanical, power electronics, and process control. The book offers the material with minimal mathematical background, making it relevant to a wide audience. Familiarity with the theoretical tools reported in the control systems literature is not necessary to understand the concepts contained within. You'll learn about a wide range of concepts, including disturbance rejection via PID control, PID control of mechanical systems, and Lyapunov stability of PID controllers. Readers will also benefit from the inclusion of: A thorough introduction to a class of physical systems described in the port-Hamiltonian form and a presentation of the systematic procedures to design PID-PBC for them An exploration of the applications to electrical, electromechanical, and process control systems of Lyapunov stability of PID controllers Practical discussions of the regulation and tracking of bilinear systems via PID control and their application to power electronics and thermal process control A concise treatment of the characterization of passive outputs, incremental models, and Port Hamiltonian and Euler-Lagrange systems Perfect for senior undergraduate and graduate students studying control systems, PID Passivity-Based Control will also earn a place in the libraries of engineers who practice in this area and seek a one-stop and fully updated reference on the subject.

This volume deals with controllability and observability properties of nonlinear systems, as well as various ways to obtain input-output representations. The emphasis is on fundamental notions as (controlled) invariant distributions and submanifolds, together with algorithms to compute the required feedbacks.

Nonlinear Control Systems and Power System Dynamics presents a comprehensive description of nonlinear control of electric power systems using nonlinear control theory, which is developed by the differential geometric approach and nonlinear robust control method. This book explains in detail the concepts, theorems and algorithms in nonlinear control theory, illustrated by step-by-step examples. In addition, all the mathematical formulation involved in deriving the nonlinear control laws of power systems are sufficiently presented. Considerations and cautions involved in applying nonlinear control theory to practical engineering control designs are discussed and special attention is given to the implementation of nonlinear control laws using microprocessors. Nonlinear Control Systems and Power System Dynamics serves as a text for advanced level courses and is an excellent reference for engineers and researchers who are interested in the application of modern nonlinear control theory to practical engineering control designs.

Selected Papers from the IFAC Symposium, Capri, Italy, 14-16 June 1989

Advanced Techniques and Applications for Linear and Nonlinear Systems

A Nonlinear Hybrid Systems Perspective

Stability in Nonlinear Control Systems

Adaptive Learning Methods for Nonlinear System Modeling

Nonlinear Control Systems Design 1992

This unique book presents an analytical uniform design methodology of continuous-time or discrete-time nonlinear control system design which guarantees desired transient performances in the presence of plant parameter variations and unknown external disturbances. All results are illustrated with numerical simulations, their practical importance is highlighted, and they may be used for real-time control system design in robotics, mechatronics, chemical reactors, electrical and electro-mechanical systems as well as aircraft control systems. The book is easy reading and is suitable for teaching.

A critical part of ensuring that systems are advancing alongside technology without complications is problem solving. Practical applications of problem-solving theories can model conflict and cooperation and aid in creating solutions to real-world problems. Soft-Computing-Based Nonlinear Control Systems Design is a critical scholarly publication that examines the practical applications of control theory and its applications in problem solving to fields including economics, environmental management, and financial modelling. Featuring a wide range of topics, such as fuzzy logic, nature-inspired algorithms, and cloud computing, this book is geared toward academicians, researchers, and students seeking relevant research on control theory and its practical applications.

"Analysis and Design of Nonlinear Control Systems" provides a comprehensive and up to date introduction to nonlinear control systems, including system analysis and major control design techniques. The book is self-contained, providing sufficient mathematical foundations for understanding the contents of each chapter. Scientists and engineers engaged in the field of Nonlinear Control Systems will find it an extremely useful handy reference book. Dr. Daizhan Cheng, a professor at Institute of Systems Science, Chinese Academy of Sciences, has been working on the control of nonlinear systems for over 30 years and is currently a Fellow of IEEE and a Fellow of IFAC, he is also the chairman of Technical Committee on Control Theory, Chinese Association of Automation.

Provides complete coverage of both the Lyapunov and Input-Output stability theories, in a readable, concise manner. * Supplies an introduction to the popular backstepping approach to nonlinear control design * Gives a thorough discussion of the concept of input-to-state stability * Includes a discussion of the fundamentals of feedback linearization and related results. * Details complete coverage of the fundamentals of dissipative system's theory and its application in the so-called L2gain control problem, for the first time in an introductory level textbook. * Contains a thorough discussion of nonlinear observers, a very important problem, not commonly encountered in textbooks at this level. *An Instructor's Manual presenting detailed solutions to all the problems in the book is available from the Wiley editorial department.

Proceedings from the 3rd IFAC Workshop, Nagoya, Japan, July 2006

Analysis, Control and Optimal Operations in Hybrid Power Systems

Computer-aided Nonlinear Control System Design

Nonlinear Control and Filtering Using Differential Flatness Approaches

Nonlinear Control Systems 2004

Nonlinear Dynamical Control Systems

Nonlinear Control Systems and Power System Dynamics Springer Science & Business Media

Designed for one-semester introductory senior-or graduate-level course, the authors provide the student with an introduction of analysis techniques used in the design of nonlinear and optimal feedback control systems. There is special emphasis on the fundamental topics of stability, controllability, and optimality, and on the corresponding geometry associated with these topics. Each chapter contains several examples and a variety of exercises.

There has been much excitement over the emergence of new mathematical techniques for the analysis and control of nonlinear systems. In addition, great technological advances have bolstered the impact of analytic advances and produced many new problems and applications which are nonlinear in an essential way. This book lays out in a concise mathematical framework the tools and methods of analysis which underlie this diversity of applications.

The author, a Nobel prize-winner, has added to the American translation several chapters not in the original. Originally published in 1961. The Princeton Legacy Library uses the latest print-on-demand technology to again make available previously out-of-print books from the distinguished backlist of Princeton University Press. These editions preserve the original texts of these important books while presenting them in durable paperback and hardcover editions. The goal of the Princeton Legacy Library is to vastly increase access to the rich scholarly heritage found in the thousands of books published by Princeton University Press since its founding in 1905.

Nonlinear Control of Dynamic Networks

Robust Event-Triggered Control of Nonlinear Systems

Advanced Topics in Nonlinear Control Systems

Nonlinear Systems Analysis

Nonlinear Control Synthesis for Electrical Power Systems Using Controllable Series Capacitors

Discrete-Time Inverse Optimal Control for Nonlinear Systems

This volume represents most aspects of the rich and growing field of nonlinear control. These proceedings contain 78 papers, including six plenary lectures, striking a balance between theory and applications. Subjects covered include feedback stabilization, nonlinear and adaptive control of electromechanical systems, nonholonomic systems. Generalized state space systems, algebraic computing in nonlinear systems theory, decoupling, linearization and model-matching and robust control are also covered.

The purpose of this book is to present a self-contained description of the fundamentals of the theory of nonlinear control systems, with special emphasis on the differential geometric approach. The book is intended as a graduate text as well as a reference to scientists and engineers involved in the analysis and design of feedback systems. The first version of this book was written in 1983, while I was teaching at the Department of Systems Science and Mathematics at Washington University in St. Louis. This new edition integrates my subsequent teaching experience gained at the University of Illinois in Urbana-Champaign in 1987, at the Carl-Cranz Gesellschaft in Oberpfaffenhofen in 1987, at the University of California in Berkeley in 1988. In addition to a major rearrangement of the last two Chapters of the first version, this new edition incorporates two additional Chapters at a more elementary level and an exposition of some relevant research findings which have occurred since 1985.

Dynamic estimation and control is a fast growing and widely researched field of study that lays the foundation for a new generation of technologies that can dynamically, adaptively and automatically stabilize power systems. This book provides a comprehensive introduction to research techniques for real-time estimation and control of power systems. Dynamic Estimation and Control of Power Systems coherently and concisely explains key concepts in a step by step manner, beginning with the fundamentals and building up to the latest developments of the field. Each chapter features examples to illustrate the main ideas, and effective research tools are presented for signal processing-based estimation of the dynamic states and subsequent control, both centralized and decentralized, as well as linear and nonlinear. Detailed mathematical proofs are included for readers who desire a deeper technical understanding of the methods. This book is an ideal research reference for engineers and researchers working on monitoring and stability of modern grids, as well as postgraduate students studying these topics. It serves to deliver a clear understanding of the tools needed for estimation and control, while also acting as a basis for readers to further develop new and improved approaches in their own research. Offers the first concise, single resource on dynamic estimation and control of power systems Provides both an understanding of estimation and control concepts and a comparison of results Includes detailed case-studies, including MATLAB codes, to explain and demonstrate the concepts presented

Whereas power systems have traditionally been designed with a focus on protecting them from routine component failures and atypical user demand, we now also confront the fact that deliberate attack intended to cause maximum disruption is a real possibility. In response to this changing environment, new concepts and tools have emerged that address many of the issues facing power system operation today. This book is aimed at introducing these ideas to practicing power systems engineers, control systems engineers interested in power systems, and graduate students in these areas. The ideas are examined with an emphasis on how they can be applied to improve our understanding of power system behavior and help design better control systems. The book is supplemented by a Mathematica package enabling readers to work out nontrivial examples and problems. Also included is a set of Mathematica tutorial notebooks providing detailed solutions of the worked examples in the text. In addition to Mathematica, simulations are carried out using Simulink with Stateflow.

Analysis and Design of Nonlinear Control Systems

Nonlinear Systems

Nonlinear Power Flow Control Design

Dynamic Estimation and Control of Power Systems