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*Key Message: This book aims to
explain physics in a readable*

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and interesting manner that is accessible and clear, and to teach readers by anticipating their needs and difficulties without oversimplifying. Physics is a description of reality, and thus each topic begins with

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concrete observations and experiences that readers can directly relate to. We then move on to the generalizations and more formal treatment of the topic. Not only does this make the material more interesting and

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*easier to understand, but it is
closer to the way physics is
actually practiced. Key Topics:
INTRODUCTION,
MEASUREMENT, ESTIMATING,
DESCRIBING MOTION:
KINEMATICS IN ONE*

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*DIMENSION, KINEMATICS IN
TWO OR THREE DIMENSIONS;
VECTORS, DYNAMICS:
NEWTON'S LAWS OF MOTION
, USING NEWTON'S LAWS:
FRICTION, CIRCULAR
MOTION, DRAG FORCES,*

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*GRAVITATION AND
NEWTON'S6 SYNTHESIS ,
WORK AND ENERGY ,
CONSERVATION OF ENERGY ,
LINEAR MOMENTUM ,
ROTATIONAL MOTION ,
ANGULAR MOMENTUM;*

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*GENERAL ROTATION , STATIC
EQUILIBRIUM; ELASTICITY
AND FRACTURE , FLUIDS ,
OSCILLATIONS , WAVE
MOTION, SOUND ,
TEMPERATURE, THERMAL
EXPANSION, AND THE IDEAL*

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OF GASES, HEAT AND THE
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EARLY QUANTUM THEORY
AND MODELS OF THE ATOM,
QUANTUM MECHANICS,
QUANTUM MECHANICS OF
ATOMS, MOLECULES AND*

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AND RADIOACTIVITY,
NUCLEAR ENERGY: EFFECTS
AND USES OF RADIATION,
ELEMENTARY
PARTICLES, ASTROPHYSICS
AND COSMOLOGY Market*

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Description: This book is written for readers interested in learning the basics of physics.

This book offers a collection of original peer-reviewed contributions presented at the 7th International Congress on

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*Design and Modeling of
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(CMSM'2017), held in
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27th to the 29th of March 2017. It
reports on both research
findings, innovative industrial*

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concerning mechanical systems
and related to modeling and
analysis of materials and
structures, multiphysics
methods, nonlinear dynamics,
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*for academic and industry
specialists active in the field of
design and modeling of
mechanical systems.*

*CMSM'2017 was jointly
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This book presents state-of-the-art research, challenges and solutions in the area of human–robot collaboration (HRC) in manufacturing. It enables readers to better understand the dynamic

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behaviour of manufacturing processes, and gives more insight into on-demand adaptive control techniques for industrial robots. With increasing complexity and dynamism in today's manufacturing practice,

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more precise, robust and practical approaches are needed to support real-time shop-floor operations. This book presents a collection of recent developments and innovations in this area, relying on a wide range

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of research efforts. The book is divided into five parts. The first part presents a broad-based review of the key areas of HRC, establishing a common ground of understanding in key aspects. Subsequent chapters focus on

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selected areas of HRC subject to intense recent interest. The second part discusses human safety within HRC. The third, fourth and fifth parts provide in-depth views of relevant methodologies and algorithms.

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Discussing dynamic planning and monitoring, adaptive control and multi-modal decision making, the latter parts facilitate a better understanding of HRC in real situations. The balance between scope and depth, and

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theory and applications, means this book appeals to a wide readership, including academic researchers, graduate students, practicing engineers, and those within a variety of roles in manufacturing sectors.

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and aims to enhance the
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and secondary agriculture
teachers.**

**Control systems have
come to play an
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performance of modern vehicles with regards to meeting goals on low emissions and low fuel consumption. To achieve these goals, modeling, simulation, and analysis

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**have become standard
tools for the development
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**treatment of the topic
from a clear perspective
of systems engineering
and control systems,
which are at the core of
vehicle design. This book
has three main goals. The**

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**first is to provide a
thorough understanding
of component models as
building blocks. It has
therefore been important
to provide measurements
from real processes, to**

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explain the underlying physics, to describe the modeling considerations, and to validate the resulting models experimentally. Second, the authors show how the

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**models are used in the
current design of control
and diagnosis systems.
These system designs are
never used in isolation, so
the third goal is to
provide a complete**

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**setting for system
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Publications

This book presents a range of dynamic programming (DP) techniques applied to the optimization of dynamical systems.

SSC Junior Engineer

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includes additional diagrams and worked examples throughout. New topics include digital interfacing and control of drives, direct torque control of induction motors and current-fed operation in DC drives. The material on brushless servomotors has also been expanded. Austin Hughes' approach,

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***The topic of consciousness is
truly multidisciplinary, attracting
researchers and theorists from***

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diverse backgrounds. It is now widely accepted that previously disparate areas all have contributions to make to the understanding of the nature of consciousness. Thus, we now have computational scientists,

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***neuroscientists, and
philosophers all engaged in the
same effort. This book illustrates
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The first section is concerned with philosophical approaches to consciousness. One of the fundamental issues here is that of subjective feeling or qualia. The second section focuses on approaches from cognitive

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neuroscience. Patients with different types of neurological problems, and new imaging techniques, provide rich sources of data for studying how consciousness relates to brain function. The third section

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reports that its reserves have been overstated by 20 percent, while the Saudis say they are already producing as much as they can. In the meantime, automobile use in China and India is rising rapidly, and 95

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percent of U.S. transportation runs on petroleum. Though improved fuel economy, hybrids, bio-fuels, and alternate fuels will help meet ever-rising demand, they will not be enough. "The Transportation Solution: Kicking

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solve Mechanical Engineering problems. It is developed to improve the programming skills of students and engineers and teach them how to use MATLAB for everyday engineering problems at school and at work.

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All the chapters contain detailed theory along with solved examples. Exhaustive question bank at the end of each chapter is provided in the form of Exercise. Solutions to the Exercise have been provided at

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membranes, and soluble conducting polymers. It also focuses on preparing and modifying conductive surface of polymer or polymer-based materials.

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